

Tutorial
on
Symbolic Computing
with *Mathematica*

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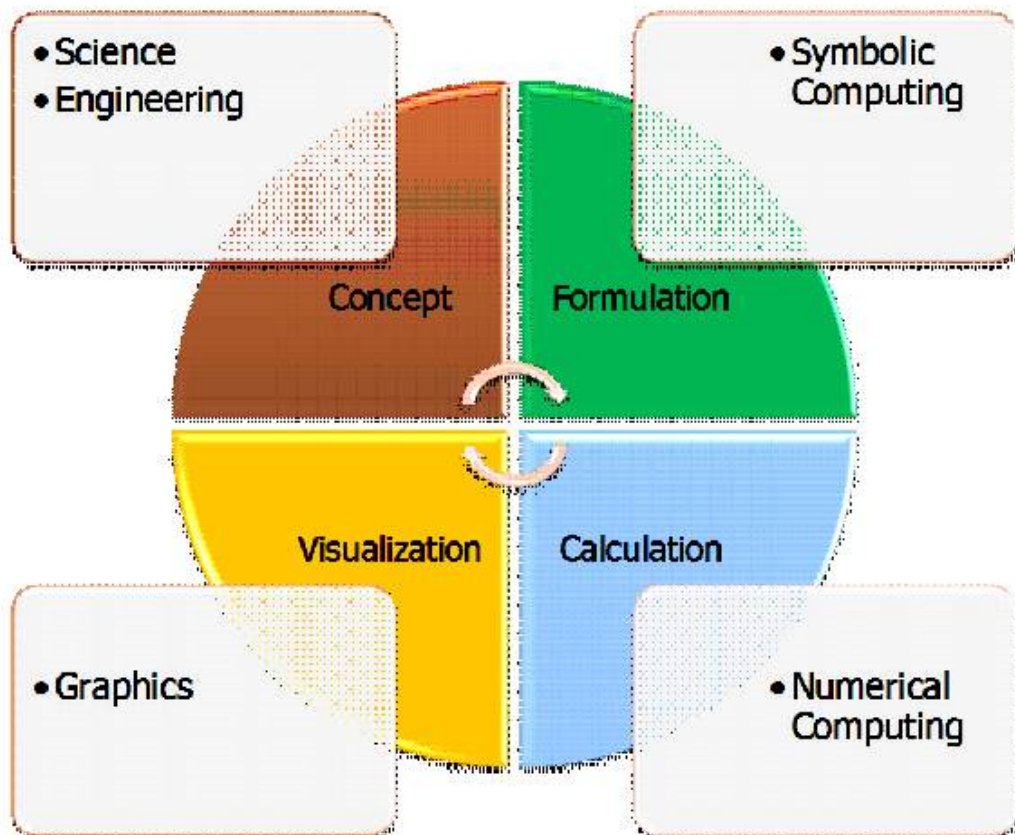
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```
<< InitPackages`
```

Symbolic Computation

- Symbolic computation (algebraic manipulation)
 - Mathematical computation with variables and constants according to the rules of algebra



- Commercial software

Mathematica

Maple

MathCad

Matlab

Reduce

Macsyma

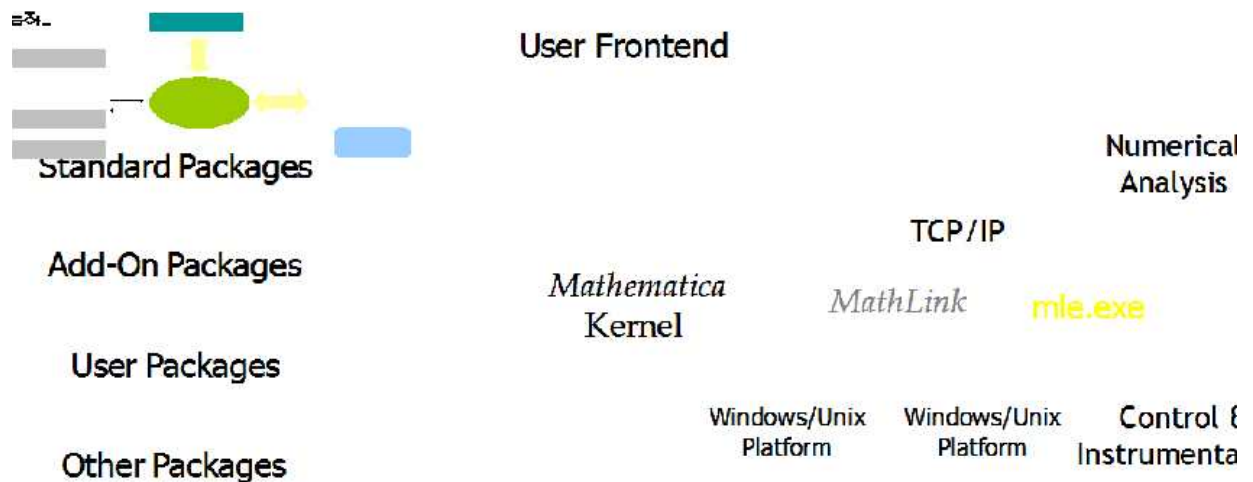
Scratchpad

Derive

Basic Concepts of *Mathematica*

- *Mathematica* is the world's only fully integrated environment for formulation, calculation and visualization for technical computing.
- The concept of *Mathematica* is to create once and for all a single system that could handle all the various aspects of technical computing in a coherent and unified way.

- The concept of *Mathematica* is to create once and for all a single system that could handle all the various aspects of technical computing in a coherent and unified way.
- Manipulation of the very wide range of objects involved in technical computing using only a fairly small number of basic primitives (over 3,000 built in the kernel of version 7).
- The functionality can be easily extended through user-defined functions and external programs.
- Platform-independent interactive documents known as notebooks (.nb files)
- System-provided macros and user-defined macros in packages (.m files)
- Interactive and non-interactive sessions
- Communication with external programs using *MathLink*
- *Mathematica* computing environment



- External applications are written in C/C++.
- *Mathematica* is used for both data input and output.
- External applications and *Mathematica* communicate via *MathLink*.
- The functionality can be extended through user-defined functions and external programs.
- More information available at <http://www.wolfram.com>

Algebraic Calculation

- Algebraic Calculations (*Mathematica Tutorial*)
 - Symbolic Calculations (*Mathematica Tutorial*)
 - Expand
 - Factor
 - Apart
 - Together
 - Simplify
-

Basic Algebra

- Polynomial Algebra (*Mathematica Guide*)
 - Polynomial Systems (*Mathematica Guide*)
-

Elementary Functions

- Elementary Functions (*Mathematica Guide*)
-

Trigonometric Functions

- Trigonometric Functions (*Mathematica Guide*)
 - Trigonometric Expressions (*Mathematica Tutorial*)
-

Complex Variables

- Complex Numbers (*Mathematica Guide*)
 - Functions of Complex Variables (*Mathematica Guide*)
-

Flow Control

- Conditionals (*Mathematica Guide*)
 - Loops and Control Structures (*Mathematica Tutorial*)
 - Flow Control (*Mathematica Guide*)
-

Formula Manipulation

Formula Manipulation

- **Formula Manipulation** (*Mathematica Guide*)
 - **Manipulating Equations** (*Mathematica Guide*)
-

User Package Functions

- Mathematica provides a solid foundation for symbolic computing and a number of supporting functions.
 - Built-in kernel functions
 - User-defined functions to complement the built-in kernel functions
- A mechanism is needed to facilitate the algebraic manipulation of mathematical expressions with the following properties:
 - Seamless integration with the computing environment of Mathematica
 - Selective targeting of the object to apply functions
 - Improved handling of subscripts (a_1), tildes (\tilde{a}), hats (\hat{a}), etc.
 - On-line setting and clearing of attributes
 - Addition of comments
 - Improved handling of derivatives, integrals and summations
 - Minimal use of variables
- Algebraic manipulation of formulas using symbolic computing
 - Mathematica is not a word processor or an equation editor.
 - Application of functions
 - Substitution using mathematical identities
 - Allows focusing on the principles instead of time-consuming and error-prone calculations.
 - Good readability
 - Minimization of human errors during calculations
 - Expressions that closely resemble the traditional mathematical style, e.g., subscripts and vector notations
- A large collection of user-defined functions
 - Basic Algebra
 - Differentiation
 - Integration
 - Summation
 - Trigonometric Functions
 - Complex Variables
 - Vectors and Matrices
 - Polynomials and Series
 - Functional Analysis
 - Equations
 - Operator Analysis
 - Plotting
 - Etc.

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 - Etc.
- **MPMAF**
 - An abbreviation of **MPMapApplyFunc**
 - The platform for algebraic manipulation of all or parts of an expression
- User-defined functions
 - The function names start with the prefix “MP”.
 - Algebraic manipulation of expressions
 - Mathematical identities
 - Can be used separately independent of the macro **MPMAF**, in which case the features provided by the options of **MPMAF** cannot be used.

Basic Algebra

- Expansion

```
Expand[(x + a)^2]
```

$$a^2 + 2 a x + x^2$$

The power exponent must be an integer. Otherwise, use **MPExpandBinomial**.

```
MPExpandBinomial[(x + a)^n, k]
MPEvalSum[%]
```

$$\sum_{k=0}^n \frac{a^k x^{-k+n} n!}{k! (-k+n)!}$$

$$(a + x)^n$$


```


$$\frac{dy}{dx} == 2 e^x y$$

MPMAF [% , MPSepVars , {All , x , Side → Right} ,
MPDiffToInt , {All , x , y , Constant →  $\frac{1}{2} \text{Log}[c_1]$ } ,
MPEvalInt , All ,
MPSolve , {All , y} ]

```

$$\frac{dy}{dx} == 2 e^x y$$

$$\frac{\text{Log}[y]}{2} == e^x + \frac{\text{Log}[c_1]}{2}$$

$$y == e^{2e^x} c_1$$

Direct solution using **MPDSolve**

```


$$\frac{dy}{dx} == 2 e^x y$$

MPMAF [% , MPDSolve , {All , y , x , RCN → c_1} ]

```

$$\frac{dy}{dx} == 2 e^x y$$

$$y == e^{2e^x} c_1$$

Trigonometric Functions

- Adding sin and cos functions

```
MPTrigAddSinCos [a Cos [x] + b Sin [x] , Sin]
```

$$\sqrt{a^2 + b^2} \text{Sin}[x + \text{ArcTan}[b, a]]$$

- Conversion to other functions

```
MPTrigConvert [Tan [x] , Cos]
```

$$\sqrt{1 - \text{Cos}[x]^2} \text{Sec}[x]$$

- Conversion to half angle

```
MPTrigToHalf [Cos [2 x] , Sin]
```

$$1 - 2 \text{Sin}[x]^2$$

- Conversion to double angle


```
MPTrigToDouble[Cos[x]^2, Cos]
```

$$\frac{1}{2} (1 + \cos[2x])$$

Complex Variables

- Asterisk (*) is interpreted as the complex conjugate

```
MPCComplexExpand[(e^{u+v})*, u, TargetFunctions -> Conjugate]
```

$$e^{v+u^*}$$

The built-in function `ComplexExpand` gives a rather different (even though equivalent) result.

```
ComplexExpand[Conjugate[e^{u+v}], u, TargetFunctions -> Conjugate]
```

$$e^{v+\frac{1}{2}(u+\text{Conjugate}[u])} \cosh\left[\frac{1}{2}(u-\text{Conjugate}[u])\right] - e^{v+\frac{1}{2}(u+\text{Conjugate}[u])} \sinh\left[\frac{1}{2}(u-\text{Conjugate}[u])\right]$$

- The exponential form of a complex number

```
MPCComplexToExp[x + i y]
```

$$e^{i \text{ArcTan}\left[\frac{y}{x}\right]} \sqrt{x^2 + y^2}$$

Polynomials and Series

- Eliminate the second highest order term

```
MPMergePoly[x^3 + a x^2 + c, x]
```

$$-\frac{a^3}{27} + c - \frac{a^2 x}{3} + \left(\frac{a}{3} + x\right)^3$$

- Transform a polynomial by making a replacement of the variable

```
MPTransPoly[x^3 + a x^2 + c, x, a + x]
```

$$c + a^2 (a + x) - 2 a (a + x)^2 + (a + x)^3$$

A case of two variables

```
MPTransPoly[x^2 (y + a), {x, y}, {x - 1, y + 1}]
```

$$a + (-2 + 2 a) (-1 + x) + (-1 + a) (-1 + x)^2 + y + 2 (-1 + x) (1 + y) + (-1 + x)^2 (1 + y)$$

- Taylor series

```
MPTaylor[ $\sqrt{1+x}$ , x, 3]
```

$$1 + \frac{x}{2} - \frac{x^2}{8} + \frac{x^3}{16}$$

```
MPTaylor[ $\sqrt{1+(x+\Delta x)^2}$ ,  $\Delta x$ , 1]
```

$$\sqrt{1+x^2} + \frac{x \Delta x}{\sqrt{1+x^2}}$$

```
MPAFE[y[x], MPTaylor, {All, x - x_0, 2, Variables -> x}, CS -> x_0, Head -> TildeTilde]
```

$$y[x] \approx y[x_0] + (x - x_0) y'[x_0] + \frac{1}{2} (x - x_0)^2 y''[x_0]$$

Equations

- Adding equations

```
MPAddEqs[{a == b, c == d, e == f}]
```

$$a + c + e == b + d + f$$

- Subtracting equations

```
MPSubtEqs[{a == b, c == d, e == f}]
```

$$a - c - e == b - d - f$$

- Move a subpart of an equation to left- or right-hand side

```
MPMoveEq[x + y == z, y, Right]
```

$$-x + z == y$$

- Eliminating variables from a set of equations

```
MPEli[{x + y == 1, x - y + 2 z == 1, y - 3 z == 3}, {y, z}] // Simplify
```

$$2x == 5$$

- Solve equations and write

```
MPSolve[{x + y == 1, x - y + 2 z == 1, y - 3 z == 3}, {x, y, z}]
```

$$\left\{ x == \frac{5}{2}, y == -\frac{3}{2}, z == -\frac{3}{2} \right\}$$

Differentiation

- The built-in derivative operator D , or ∂ , evaluates the expression immediately.

```
D[f[x], x]
```

 $f'[x]$

The total derivative operator Dt assumes all symbols are dependent variables.

```
Dt[a f[x], x]
```

 $Dt[a, x] f[x] + a f'[x]$

- The partial differential operator $\frac{\partial}{\partial x}$ delays the evaluation until the command **MPEvalD** or **MPExpandD** is encountered.

```
y =  $\frac{\partial^3}{\partial x^2 \partial y}$  (a f + b g)
MPMAF[%, MPExpandD, {At[2], {f, g}}]
```

$$y = \frac{\partial^3 (a f + b g)}{\partial x^2 \partial y}$$

$$y = a \frac{\partial^3 f}{\partial x^2 \partial y} + b \frac{\partial^3 g}{\partial x^2 \partial y}$$

The function **MPExpandD** is used to expand an expression using the differential operators.

```
MPExpandD[ $\frac{\partial}{\partial x} \left( \frac{f + \text{Sin}[g]}{h} \right)$ , {f, g, h}]
```

$$\frac{1}{h} \left(\frac{\partial f}{\partial x} + \text{Cos}[g] \frac{\partial g}{\partial x} \right) - \frac{f + \text{Sin}[g]}{h^2} \frac{\partial h}{\partial x}$$

- Integration by parts using the differential operator

```
MPIntegrateByPartsD[HF@ $\int f \frac{\partial g}{\partial x} dx$ ]
```

$$f g - \int g \frac{\partial f}{\partial x} dx$$

- Merging the differential operator

```
MPMergeD[a  $\frac{\partial f}{\partial x}$  + b  $\frac{\partial g}{\partial x}$ ]
```

$$\frac{\partial (a f + b g)}{\partial x}$$

- Transformation of variables

- Transformation of variables

$$\text{MPTransD}\left[\frac{\partial^2 \phi}{\partial \omega^2}, \text{VT} \rightarrow \left\{\omega, \lambda, \omega = \frac{2 \pi c}{\lambda}\right\}\right]$$

$$\frac{\lambda^3}{2 c^2 \pi^2} \frac{\partial \phi}{\partial \lambda} + \frac{\lambda^4}{4 c^2 \pi^2} \frac{\partial^2 \phi}{\partial \lambda^2}$$

- Evaluation of vector operators

```
MPAFE [∇² ψ, MPEvalVecOps, {All, ψ == ψ[ρ, φ], Cylindrical[ρ, φ, z]}, Apply → Expand]
```

```
MMAF [% , MPSimpD, {1/ρ ∂ψ/∂ρ + ∂²ψ/∂ρ², Mult → ρ}]
```

$$\nabla^2 \psi = \frac{1}{\rho} \frac{\partial \psi}{\partial \rho} + \frac{\partial^2 \psi}{\partial \rho^2} + \frac{1}{\rho^2} \frac{\partial^2 \psi}{\partial \varphi^2}$$

$$\nabla^2 \psi = \frac{1}{\rho^2} \frac{\partial^2 \psi}{\partial \varphi^2} + \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \psi}{\partial \rho} \right)$$

```
MPAFE [∇² ψ, MPEvalVecOps, {All, ψ == ψ[x, y, z], Cartesian[x, y, z]}]
```

```
MMAF [% , MPTransD, {At[2],
```

```
VT → {{x, y, z}, {r, θ, φ}, {x == r Sin[θ] Cos[φ], y == r Sin[θ] Sin[φ], z == r Cos[θ]}},  
Apply → (Expand@PowerExpand@Simplify@# &)},
```

```
MPSimpD, {{2/r ∂ψ/∂r + ∂²ψ/∂r²}, {Cot[θ]/r² ∂ψ/∂θ + 1/r² ∂²ψ/∂θ²}}}]
```

$$\nabla^2 \psi = \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2}$$

$$\nabla^2 \psi = \frac{2}{r} \frac{\partial \psi}{\partial r} + \frac{\text{Cot}[\theta]}{r^2} \frac{\partial \psi}{\partial \theta} + \frac{\partial^2 \psi}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2} + \frac{\text{Csc}[\theta]^2}{r^2} \frac{\partial^2 \psi}{\partial \varphi^2}$$

$$\nabla^2 \psi = \frac{\text{Csc}[\theta]^2}{r^2} \frac{\partial^2 \psi}{\partial \varphi^2} + \frac{1}{r} \frac{\partial^2 (r \psi)}{\partial r^2} + \frac{\text{Csc}[\theta]}{r^2} \frac{\partial}{\partial \theta} \left(\sin[\theta] \frac{\partial \psi}{\partial \theta} \right)$$

Integration

- Wrap the integral with **HoldForm** (HF) to prevent evaluation.

– Without the wrap

$$\mathbf{F} = \int \mathbf{f}[\mathbf{x}] \, d\mathbf{x}$$

$$F = \int f[x] \, dx$$

– With the wrap

$$F == \text{HF@} \int f \, dx$$

$$F == \int f \, dx$$

- Combining multiple integrals

$$\left(\text{HF@} \int f[x] \, dx \right) \left(\text{HF@} \int g[x] \, dx \right)$$

$$\text{MPCombInt}[\%, \text{RV} \rightarrow \{x, x'\}]$$

$$\left(\int f[x] \, dx \right) \int g[x] \, dx$$

$$\iint f[x] g[x'] \, dx' \, dx$$

- Convolution in Fourier transform

$$\{f[x] == \text{HF@} \int F[k] e^{ikx} \, dk, g[x] == \text{HF@} \int G[k] e^{ikx} \, dk\}$$

$$\{f[x] == \int F[k] e^{ikx} \, dk, g[x] == \int G[k] e^{ikx} \, dk\}$$

$$\text{HF@} \int F[k] G[k] e^{ikx} \, dk$$

$$\text{MPMAF}[\%, \text{RA}, \{\text{All}, \{F[k] == \frac{1}{2\pi} \int f[x] e^{-ikx} \, dx, G[k] == \frac{1}{2\pi} \int g[x] e^{-ikx} \, dx\}\},$$

$$\text{MPCombInt}, \{\text{All}, \text{RV} \rightarrow \{x, x', x''\}\},$$

$$\text{MPFourierToDiracDelta}, \{\text{All}, k\},$$

$$\text{MPEvalIntDelta}, \{\text{All}, x''\}]$$

$$\int F[k] G[k] e^{ikx} \, dk$$

$$\frac{1}{2\pi} \int \left(\int f[x''] g[x'] \delta[x - x' - x''] \, dx' \right) \, dx''$$

$$\frac{1}{2\pi} \int f[x - x'] g[x'] \, dx'$$

- Transformation of the integration variables

$$\text{MPTransInt} \left[\int f \, dx, \text{VT} \rightarrow \{x, y, y == x^2\} \right]$$

$$\int \frac{f}{2\sqrt{y}} \, dy$$

$$\text{MPAFE} \left[\text{HF@} \int_{-\infty}^{\infty} \frac{1}{x^2 + a^2} \, dx, \text{MPEvalInt}, \text{Apply} \rightarrow \text{PowerExpand} \right]$$

$$\int_{-\infty}^{\infty} \frac{1}{x^2 + a^2} \, dx == \frac{\pi}{a}$$

```
MPAFE [HF@  $\int_{-\infty}^{\infty} \frac{1}{x^2 + a^2} dx$ , MPTransInt,
{All, VT → {x,  $\theta$ , x == a Tan[ $\theta$ ]}, RA → Sign[a] == 1, PostApply → MPEvalInt]
```

$$\int_{-\infty}^{\infty} \frac{1}{x^2 + a^2} dx = \frac{\pi}{a}$$

```
HF@Integrate[f, x, y, z]
MPMAF[%, MPTransInt, {All,
VT → {{x, y, z}, {r,  $\theta$ ,  $\phi$ }, {x == r Sin[ $\theta$ ] Cos[ $\phi$ ], y == r Sin[ $\theta$ ] Sin[ $\phi$ ], z == r Cos[ $\theta$ ]}}},
Apply → PowerExpand]
```

$$\iiint f dz dy dx$$

$$\iiint f r^2 \sin[\theta] d\phi d\theta dr$$

- Replacement of the integration variable with others

```
MPTransInt [ $\int f dx^3$ , Weight →  $r^2 \sin[\theta]$ , RV → { $x^3$ , {r, 0,  $\infty$ }, { $\theta$ , 0,  $\pi$ }, { $\phi$ , 0,  $2\pi$ }}
```

$$\int_0^{\infty} \int_0^{\pi} \int_0^{2\pi} f r^2 \sin[\theta] d\phi d\theta dr$$

- Merging multiple integrals

```
MPMergeInt [a  $\int f dx$  + b  $\int g dx$  + c  $\int h dx$ ]
```

$$\int (a f + b g + c h) dx$$

- Merging integration intervals

```
MPMergeIntInterval [ $\int_0^a f[t] dt$  +  $\int_a^b f[t] dt$ ]
```

$$\int_0^b f[t] dt$$

- Integration by parts

```
MPIntegrateByParts [HF@  $\int_{-\infty}^x \psi'[y] y^2 dy$ ,  $\psi'[y]$ ]
```

$$-\int_{-\infty}^x 2 y \psi[y] dy - (y^2 \psi[y])_{y=-\infty} + x^2 \psi[x]$$

Summation

- Changing the summation intervals

$$\text{MPChSumInterval} \left[\text{HF@} \sum_{n=-\infty}^{\infty} a_n, \{n, \{1, 2\}, \{n_3, n_4\}\} \right]$$

$$\sum_{n=1}^2 a_n + \sum_{n=n_3}^{n_4} a_n$$

- Combining multiple summations. The indexes are replaced to avoid duplication.

$$\text{MPCombSum} \left[\sum_{n=1}^{\infty} f_n \sum_{n=1}^{\infty} g_n, \text{RV} \rightarrow \{n, m\} \right]$$

$$\sum_{n=1}^{\infty} \sum_{m=1}^{\infty} f_n g_m$$

- Merging multiple summations

$$\text{MPMergeSum} \left[\sum_{k=0}^{\infty} A[k] + \sum_{k=0}^{\infty} B[k] \right]$$

$$\sum_{k=0}^{\infty} (A[k] + B[k])$$

- Merging summation intervals

$$\text{MPMergeSumInterval} \left[\sum_{n=0}^{k-1} a_n + \sum_{n=k}^N a_n \right]$$

$$\sum_{n=0}^N a_n$$

Vectors and Matrices

- Expansion of vector expressions

$$\text{MPExpandVec} \left[\vec{A} \times (\mathbf{a} \vec{B} \times \vec{C}) \right]$$

$$\mathbf{a} \vec{A} \cdot \vec{C} \vec{B} - \mathbf{a} \vec{A} \cdot \vec{B} \vec{C}$$

$$\text{MPExpandVec} \left[\nabla \cdot (\epsilon \vec{E}), \{\epsilon, \vec{E}\} \right]$$

$$\epsilon \nabla \cdot \vec{E} + (\nabla \epsilon) \cdot \vec{E}$$

- Matrix form of equations

$$\text{MPEqsMatForm} \left[\{\mathbf{a} \mathbf{x} + \mathbf{b} \mathbf{y} = \mathbf{z}_1, \mathbf{c} \mathbf{x} + \mathbf{d} \mathbf{y} = \mathbf{z}_2\}, \{\mathbf{x}, \mathbf{y}\} \right]$$

$$\begin{pmatrix} \mathbf{a} & \mathbf{b} \\ \mathbf{c} & \mathbf{d} \end{pmatrix} \cdot \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} \mathbf{z}_1 \\ \mathbf{z}_2 \end{pmatrix}$$

- Expansion of $\nabla \times \nabla \times \nabla \mathbf{A}$

- Expansion of $\nabla \times \nabla \times \nabla \mathbf{A}$

```
MPExpandVec [∇ × ∇ ×  $\vec{A}$ ,  $\vec{A}$ ]
```

$$\nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$$

- Deleting a column from a matrix

```
Table[i j, {i, 3}, {j, 3}] // MatrixForm  
MPDeleteColumns [% , 2] // MatrixForm
```

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 \\ 2 & 6 \\ 3 & 9 \end{pmatrix}$$

- Inserting a column in a matrix

```
Table[i j, {i, 3}, {j, 3}] // MatrixForm  
MPInsertColumns [% , {0, 0, 0}, -1] // MatrixForm
```

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & 0 \\ 2 & 4 & 6 & 0 \\ 3 & 6 & 9 & 0 \end{pmatrix}$$

- Diagonalization of a matrix

```
 $\begin{pmatrix} 1 & 4 & 9 \\ 4 & 4 & 0 \\ 9 & 0 & 4 \end{pmatrix}$ ;  
MPDiagMatrix [%] // MatrixForm
```

$$\begin{pmatrix} \frac{1}{2} (5 + \sqrt{397}) & 0 & 0 \\ 0 & \frac{1}{2} (5 - \sqrt{397}) & 0 \\ 0 & 0 & 4 \end{pmatrix}$$

- Transform a vector from Cartesian to spherical coordinates

```
MPVecFromCart[{0, 0, 1}, Spherical[r,  $\theta$ ,  $\varphi$ ]]
```

$$\{\cos[\theta], -\sin[\theta], 0\}$$

The result is $\hat{\mathbf{z}} = \hat{\mathbf{r}} \cos\theta - \hat{\boldsymbol{\theta}} \sin\theta$.

- Transform a vector from spherical to Cartesian coordinates


```
MPVecToCart[{0, 0, 1}, Spherical[r,  $\theta$ ,  $\varphi$ ]]
```

```
{-Sin[ $\varphi$ ], Cos[ $\varphi$ ], 0}
```

The result is $\hat{\varphi} = -\hat{x} \sin\varphi + \hat{y} \cos\varphi$.

Functional Analysis

- Variable transformation

```
y'[x] + y[x]
MPTransEq[%, y[x] == g[s], VT -> {x, s, x == s^2, s == sqrt[x]}]
```

```
y[x] + y'[x]
```

```
g[s] +  $\frac{g'[s]}{2s}$ 
```

A case of two variables

```
 $\partial_{x,x} f[x, y] - \partial_{y,y} f[x, y]$ 
MPTransEq[%, f[x, y] == g[ $\xi$ ,  $\eta$ ],
VT -> {{x, y}, { $\xi$ ,  $\eta$ }, { $\xi == \frac{x+y}{2}$ ,  $\eta == \frac{x-y}{2}$ }}, Apply -> Simplify]
```

```
-f(0,2)[x, y] + f(2,0)[x, y]
```

```
g(1,1)[ $\xi$ ,  $\eta$ ]
```

- Abbreviation of derivatives

```
MPAbbrevF[i p(0,1)[x, t] - 2  $\alpha$  p(1,0)[x, t] q(1,0)[x, t], Deriv -> True]
```

```
i pt - 2  $\alpha$  px qx
```

The subscripts denote the derivatives. The function arguments can be restored using `MPRestoreFunctions`.

```
MPRestoreF[i pt - 2  $\alpha$  px qx, {p, q}, Deriv -> True]
```

```
-2  $\alpha$  p(0,1)[t, x] q(0,1)[t, x] + i p(1,0)[t, x]
```

- Taking a factor out of a function

```
MPFactorFunc[f[a x] +  $\nabla \times (a A)$ , CurlH, a]
```

```
a  $\nabla \times A$  + f[a x]
```

- Putting a factor inside a function

```
MPInsideFunc[f[a x] + a ∇ × A, CurlH, a]
```

$$\nabla \times (a \mathbf{A}) + f[a x]$$

- Merging arguments of a linear function

```
MPMergeFunc[a f[x, z] + b f[y, z], f]
```

$$f[a x + b y, z]$$

Operator Analysis

- Expansion of operator expressions

```
MPExpandBraket[(⟨a| + ⟨b|) ∘ A ∘ (|α⟩ + |β⟩), A]
```

$$\langle a | A | \alpha \rangle + \langle a | A | \beta \rangle + \langle b | A | \alpha \rangle + \langle b | A | \beta \rangle$$

```
MPCommutator[
  (Q / (λ₀ √2) + i P λ₀ / (ħ √2), Q / (λ₀ √2) - i P λ₀ / (ħ √2)) P,
  MPExpandOp[%, {Q, P}]
]
```

$$\begin{aligned}
 & - \left(\frac{Q}{\sqrt{2} \lambda_0} - \frac{i P \lambda_0}{\sqrt{2} \hbar} \right) \circ \left(\frac{Q}{\sqrt{2} \lambda_0} + \frac{i P \lambda_0}{\sqrt{2} \hbar} \right) + \left(\frac{Q}{\sqrt{2} \lambda_0} + \frac{i P \lambda_0}{\sqrt{2} \hbar} \right) \circ \left(\frac{Q}{\sqrt{2} \lambda_0} - \frac{i P \lambda_0}{\sqrt{2} \hbar} \right) \\
 & \frac{i}{\hbar} P \circ Q - \frac{i}{\hbar} Q \circ P
 \end{aligned}$$

- Simplify a commutator using a commutation rule $[Q, P] \equiv QP - PQ = i \hbar$

```
MPCommutator[Q², P²]
MPSimpOp[%, {Q, P, i ħ}]
```

$$-P^2 \circ Q^2 + Q^2 \circ P^2$$

$$2 \hbar^2 + 4 i \hbar Q \circ P$$

Examples

– Ref. Chap 9, Arfken, Mathematical Methods for Physicists

■ Parachutist

- The equation of motion is

```
m v̇ = m g - b v²
```

where $-b v^2$ is the drag force and $m g$ is the force of the gravitational attraction. The initial velocity when the parachute opens at time $t = 0$ is $v(0) = v_i$.

- The terminal velocity, v_0 , can be found from the equation of motion as $t \rightarrow \infty$; when there is no acceleration, $\dot{v} = 0$, so

- The terminal velocity, v_0 , can be found from the equation of motion as $t \rightarrow \infty$; when there is no acceleration, $\dot{v} = 0$, so

```
m v̇ == m g - b v^2
MPMAF[%, RA, {All, {v̇ == 0, v == v0}},
MPSolve, {All, v0, -1}, MergeP → True]
```

$$m \dot{v} = g m - b v^2$$

$$0 = g m - b v_0^2$$

$$v_0 = \sqrt{\frac{g m}{b}}$$

- The variables t and v separate.

```
m v̇ == m g - b v^2
MPMAF[%, RA, {At[1], v̇ == dv/dt},
MPSepVars, {All, t, Times, Side → Right},
MPDivDenom, {At[1], m}]
```

$$m \dot{v} = g m - b v^2$$

$$\frac{m dv}{g m - b v^2} = dt$$

$$\frac{dv}{g - \frac{b v^2}{m}} = dt$$

which can be integrated to yield the velocity at time t .

```
dv/dt == dt
g - bv^2/m
MPMAF[%, MPDiffToInt, {All, {v, v1, v}, t}, ,
MPEvalInt, All, , ,
MPSolve, {All, v}, Hold → v1, MergeP → True, ,
TrigExpand, At[2], Apply → Simplify,
MPDivFrac, {At[2], sqrt(b/gm) Cosh[sqrt(bg/m) t]}, MergeP → True, ,
MPEli, {At[2], v0 == sqrt(gm/b), b}, Apply → PowerExpand, , ,
MPEli, {At[2], v0/g == T, g}]
```

$$\frac{dv}{g - \frac{b v^2}{m}} = dt$$

$$\int_{v_i}^v \frac{1}{g - \frac{b v^2}{m}} dv = \int 1 dt$$

$$v = \sqrt{\frac{g m}{b}} \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t + \operatorname{ArcTanh}\left[\sqrt{\frac{b}{g m}} v_i\right]\right]$$

$$v = \sqrt{\frac{g m}{b}} \frac{v_i + \sqrt{\frac{g m}{b}} \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t\right]}{\sqrt{\frac{g m}{b}} + v_i \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t\right]}$$

$$v = \frac{v_0 \left(v_i + v_0 \operatorname{Tanh}\left[\frac{t}{T}\right]\right)}{v_0 + v_i \operatorname{Tanh}\left[\frac{t}{T}\right]}$$

where

$$\left\{v_0 = \sqrt{\frac{g m}{b}}, T = \frac{v_0}{g}\right\}$$

- Verify that our solution satisfies the original equation of motion:

```
MPAFE [v, MPEExpand, {All, v == \frac{v_0 (v_i + v_0 \operatorname{Tanh}[\frac{t}{T}])}{v_0 + v_i \operatorname{Tanh}[\frac{t}{T}]}, OverDot -> t}, Apply -> Simplify]
MPMAF [%, MPTrigConvert, {At[2], Tanh},
MPEli, {At[2], v == \frac{v_0 (v_i + v_0 \operatorname{Tanh}[\frac{t}{T}])}{v_0 + v_i \operatorname{Tanh}[\frac{t}{T}]}, Tanh[\frac{t}{T}]}}, Apply -> Simplify,
RR, {At[2], {v_0 == \sqrt{\frac{g m}{b}}, T == \frac{v_0}{g}}}, Apply -> Expand]
```

$$\dot{v} = \frac{v_0 (v_0^2 - v_i^2)}{T (v_0 \operatorname{Cosh}\left[\frac{t}{T}\right] + v_i \operatorname{Sinh}\left[\frac{t}{T}\right])^2}$$

$$\dot{v} = \frac{-v^2 + v_0^2}{T v_0}$$

$$\dot{v} = g - \frac{b v^2}{m}$$

that is, Newton's equation of motion.

- Substituting the numerical data, v_0 and T are

$$\left\{ v_0 = \sqrt{\frac{g m}{b}}, T = \frac{v_0}{g} \right\}$$

```
MPMAF [% , MPEli , {All , v_0 , 1 , Keep -> True} , ExpandMergeP -> True ,
```

```
RA , {All , {g = 9.8  $\frac{\text{Meter}}{\text{Second}^2}$  , b = 700  $\frac{\text{Kilo Gram}}{\text{Meter}}$  , m = 70 Kilo Gram}} , Apply -> PowerExpand ,
```

```
Convert , {At[1 , 2] ,  $\frac{\text{Mile}}{\text{Hour}}$ }]
```

$$\left\{ v_0 = \sqrt{\frac{g m}{b}}, T = \frac{v_0}{g} \right\}$$

$$\left\{ v_0 = \frac{0.989949 \text{ Meter}}{\text{Second}}, T = 0.101015 \text{ Second} \right\}$$

$$\left\{ v_0 = \frac{2.21445 \text{ Mile}}{\text{Hour}}, T = 0.101015 \text{ Second} \right\}$$

Plot $v(t)$.

$$v = \sqrt{\frac{g m}{b}} \frac{v_i + \sqrt{\frac{g m}{b}} \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t\right]}{\sqrt{\frac{g m}{b}} + v_i \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t\right]}$$

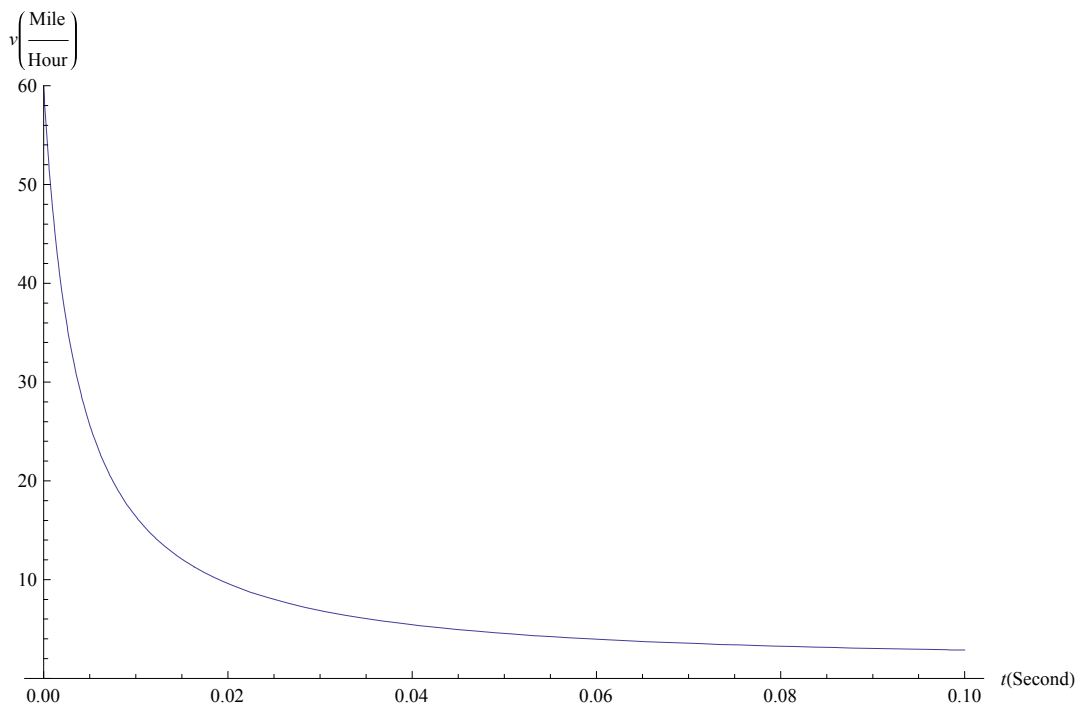
```

MPMAF [% , RA , {At[2] , {g == 9.8  $\frac{\text{Meter}}{\text{Second}^2}$  , b == 700  $\frac{\text{Kilo Gram}}{\text{Meter}}$  ,
  m == 70 Kilo Gram , v_i == 60  $\frac{\text{Mile}}{\text{Hour}}$  , t == t Second}} , Apply -> PowerExpand ,
MPDivFrac , {At[2] ,  $\frac{\text{Mile}}{\text{Hour}}$  } ,
Convert , {{  $\frac{\text{Hour Meter}}{\text{Mile Second}}$  , 1 } , {At[2] ,  $\frac{\text{Mile}}{\text{Hour}}$  } } ,
MPDivEq , {All ,  $\frac{\text{Mile}}{\text{Hour}}$  } ,
Plot , {At[2] , {t , 0 , 0.1} , PlotRange -> {0 , 60} ,
  AxesLabel -> {t[Second] , v [ $\frac{\text{Mile}}{\text{Hour}}$ ] } , ImageSize -> 500 } , Take -> Last ]

```

$$v = \sqrt{\frac{g m}{b}} \frac{v_i + \sqrt{\frac{g m}{b}} \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t\right]}{\sqrt{\frac{g m}{b}} + v_i \operatorname{Tanh}\left[\sqrt{\frac{b g}{m}} t\right]}$$

$$\frac{\text{Hour } v}{\text{Mile}} = \frac{2.21445 (60 + 2.21445 \operatorname{Tanh}[9.89949 t])}{2.21445 + 60 \operatorname{Tanh}[9.89949 t]}$$



■ Series Solution of Differential Equations

- We apply the method of series solution to the linear (classical) oscillator equation.

(9.84)

$$\frac{d^2 y}{dx^2} + \omega^2 y = 0$$

with known solutions $y = \sin(\omega x)$, $\cos(\omega x)$.

- We try the series solution of the form

(9.85)

$$y[x] = x^k (a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots) = \text{HF@} \sum_{\lambda=0}^{\infty} a_{\lambda} x^{k+\lambda}$$

$$y[x] = x^k (\dots + a_0 + x a_1 + x^2 a_2 + x^3 a_3) = \sum_{\lambda=0}^{\infty} a_{\lambda} x^{k+\lambda}$$

with $a_0 \neq 0$ and the exponent k and all the coefficients a_{λ} still undetermined.

- By substituting (9.85) into Eq. (9.84), we have

(9.86)

$$\frac{d^2 y}{dx^2} + \omega^2 y = 0$$

$$\text{MPMAF}[\%, \text{RA}, \{\text{At}[1], y = \sum_{\lambda=0}^{\infty} a_{\lambda} x^{k+\lambda}\}, \text{Apply} \rightarrow \text{MPEvalD}]$$

$$y \omega^2 + \frac{d^2 y}{dx^2} = 0$$

$$\omega^2 \sum_{\lambda=0}^{\infty} x^{k+\lambda} a_{\lambda} + \sum_{\lambda=0}^{\infty} x^{-2+k+\lambda} (-1+k+\lambda)(k+\lambda) a_{\lambda} = 0$$

which gives

$$\omega^2 \sum_{\lambda=0}^{\infty} x^{k+\lambda} a_{\lambda} + \sum_{\lambda=0}^{\infty} x^{-2+k+\lambda} (-1+k+\lambda) (k+\lambda) a_{\lambda} = 0$$

```
MPMAF [% , MPShiftSum, {At[1, x-2+k+λ], {λ, 2}},
MPChSumLimits, {At[1], {λ, 0, ∞}},
MPMergeSum, At[1],
MPFactor, {At[1], xk+λ}, Base → _Sum]
```

$$\omega^2 \sum_{\lambda=0}^{\infty} x^{k+\lambda} a_{\lambda} + \sum_{\lambda=0}^{\infty} x^{-2+k+\lambda} (-1+k+\lambda) (k+\lambda) a_{\lambda} = 0$$

$$\sum_{\lambda=0}^{\infty} (x^{k+\lambda} \omega^2 a_{\lambda} + x^{k+\lambda} (1+k+\lambda) (2+k+\lambda) a_{2+\lambda}) + (-1+k) k x^{-2+k} a_0 + k (1+k) x^{-1+k} a_1 = 0$$

$$\sum_{\lambda=0}^{\infty} x^{k+\lambda} (\omega^2 a_{\lambda} + (1+k+\lambda) (2+k+\lambda) a_{2+\lambda}) + (-1+k) k x^{-2+k} a_0 + k (1+k) x^{-1+k} a_1 = 0$$

– From the lowest power of x , x^{k-2} , vanishing of the coefficient yields

$$(-1+k) k a_0 = 0$$

Since a_0 was chosen to be nonzero, we have

(9.87)

$$(-1+k) k = 0$$

This equation is called the indicial equation and we have $k = 0$ or $k = 1$.

– Since the coefficient of x^{k+j} ($j \geq 0$) vanishes, this results in

(9.88)

$$\omega^2 a_{\lambda} + (1+k+\lambda) (2+k+\lambda) a_{2+\lambda} = 0$$

```
MPMAF [% , RA, {At[1], λ == j},
MPSolve, {All, a2+j}]
```

$$\omega^2 a_{\lambda} + (1+k+\lambda) (2+k+\lambda) a_{2+\lambda} = 0$$

$$\omega^2 a_j + (1+j+k) (2+j+k) a_{2+j} = 0$$

$$a_{2+j} = -\frac{\omega^2 a_j}{(1+j+k) (2+j+k)}$$

• Depending on whether $k = 0$ or $k = 1$, we have different recurrence relations. First with $k = 0$, the recurrence relation (Eq. (9.88)) becomes

(9.89)

$$a_{2+j} = - \frac{\omega^2 a_j}{(1+j+k)(2+j+k)}$$

```
MPMAF [% , RA , {At[2] , k == 0}]
```

$$a_{2+j} = - \frac{\omega^2 a_j}{(1+j+k)(2+j+k)}$$

$$a_{2+j} = - \frac{\omega^2 a_j}{(1+j)(2+j)}$$

whose solution is

(9.90)

$$a_{2+j} = - \frac{\omega^2 a_j}{(1+j)(2+j)}$$

```
MPMAF [% , MPRSolve , {All , a_j , {j , 0}} ,
  RA , {All , j == 2 n} , SimpOne -> True , Apply -> PowerExpand ,
  MPToFactorial , At[2]]
```

$$a_{2+j} = - \frac{\omega^2 a_j}{(1+j)(2+j)}$$

$$a_{2n} = \frac{(-1)^n \omega^{2n} a_0}{\Gamma[1+2n]}$$

$$a_{2n} = \frac{(-1)^n \omega^{2n} a_0}{(2n)!}$$

and our solution of the differential equation is

(9.91)

$$y = \sum_{\lambda=0}^{\infty} a_{\lambda} x^{k+\lambda}$$

```
MPMAF [% , RA , {At[2] , k == 0} ,
  MPChSumInterval , {At[2] , {lambda , {n , 0 , infinity , lambda == 2 n}} ,
  RA , {At[2] , a_{2n} == \frac{(-1)^n \omega^{2n} a_0}{(2n)!}} , Apply -> MPFactorSum ,
  MPEvalSum , At[2]]
```

$$y = \sum_{\lambda=0}^{\infty} a_{\lambda} x^{k+\lambda}$$

$$y = a_0 \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n} \omega^{2n}}{(2n)!}$$

$$y = \text{Cos}[x \omega] a_0$$

• Similarly, if we choose the indicial equation root $k = 1$ (Eq. (9.88)), the solution becomes

(9.94)

$$y = \frac{\sin[x \omega] a_0}{\omega}$$

- From (9.91) and (9.94), the general solution can be put

$$y = c_1 \cos[x \omega] + c_2 \sin[x \omega]$$

Mathematica Language

- Language Overview (*Mathematica* Guide)

Structure of *Mathematica* Expressions

- Expressions (*Mathematica* Tutorial)

Constants

- Numbers (*Mathematica* Overview)
- Types of Numbers (*Mathematica* Tutorial)
- Integer (Built-in *Mathematica* Symbol)
- Rational (Built-in *Mathematica* Symbol)
- Real (Built-in *Mathematica* Symbol)
- Complex (Built-in *Mathematica* Symbol)

- Mathematical Constants (*Mathematica* Guide)

Variables

- Defining Variables (*Mathematica* Tutorial)
- Eliminating Variables (*Mathematica* Tutorial)

Patterns

- Patterns (*Mathematica* Guide)
 - Introduction to Patterns
 - Verbatim Patterns
 - Example
- In four-wave mixing, two waves of frequencies ω_1 and ω_2 interact and generate additional frequencies through nonlinear mixing. Suppose the two waves are given by

$$\mathbf{E}_i = \frac{1}{2} (\tilde{\mathbf{E}}_i e^{-i \omega_i t} + \tilde{\mathbf{E}}_i^* e^{i \omega_i t})$$

for $i = 1, 2$, and the nonlinear process is due to the third-order Kerr effect:

$$\mathbf{P}_{\text{NL}} = \epsilon_0 \chi_3 \mathbf{E}^3$$

Find out what frequencies are present in the output wave near $\omega_1 \approx \omega_2$.

• The field is given by

$$\mathbf{E} = \text{HF@} \sum_{i=1}^2 \mathbf{E}_i$$

$$\text{MPMAF}[\%, \text{RA}, \{\text{At}[2], \mathbf{E}_i = \frac{1}{2} (\tilde{\mathbf{E}}_i e^{-i \omega_i t} + \tilde{\mathbf{E}}_i^* e^{i \omega_i t})\},$$

$$\text{MPEvalSum}, \text{At}[2]]$$

$$\mathbf{E} = \sum_{i=1}^2 \mathbf{E}_i$$

$$\mathbf{E} = \frac{1}{2} \sum_{i=1}^2 (e^{-i t \omega_i} \tilde{\mathbf{E}}_i + e^{i t \omega_i} (\tilde{\mathbf{E}}_i)^*)$$

$$\mathbf{E} = \frac{1}{2} (e^{-i t \omega_1} \tilde{\mathbf{E}}_1 + e^{-i t \omega_2} \tilde{\mathbf{E}}_2 + e^{i t \omega_1} (\tilde{\mathbf{E}}_1)^* + e^{i t \omega_2} (\tilde{\mathbf{E}}_2)^*)$$

and the nonlinear mixing produces

$$\mathbf{P}_{\text{NL}} = \epsilon_0 \chi_3 \mathbf{E}^3$$

$$\text{MPMAF}[\%, \text{RA}, \{\text{At}[2], \mathbf{E} = \frac{1}{2} (e^{-i t \omega_1} \tilde{\mathbf{E}}_1 + e^{-i t \omega_2} \tilde{\mathbf{E}}_2 + e^{i t \omega_1} (\tilde{\mathbf{E}}_1)^* + e^{i t \omega_2} (\tilde{\mathbf{E}}_2)^*)\},$$

$$\text{Expand}, \text{At}[2], \mathbf{E}], \text{FactorExp} \rightarrow \mathbf{i} t]$$

$$\mathbf{P}_{\text{NL}} = \mathbf{E}^3 \epsilon_0 \chi_3$$

$$\mathbf{P}_{\text{NL}} = \frac{1}{8} \epsilon_0 \chi_3 (e^{-i t \omega_1} \tilde{\mathbf{E}}_1 + e^{-i t \omega_2} \tilde{\mathbf{E}}_2 + e^{i t \omega_1} (\tilde{\mathbf{E}}_1)^* + e^{i t \omega_2} (\tilde{\mathbf{E}}_2)^*)^3$$

$$\mathbf{P}_{\text{NL}} = \frac{1}{8} \epsilon_0 \chi_3 (e^{-3 i t \omega_1} \tilde{\mathbf{E}}_1^3 + 3 e^{i t (-2 \omega_1 - \omega_2)} \tilde{\mathbf{E}}_1^2 \tilde{\mathbf{E}}_2 + 3 e^{i t (-\omega_1 - 2 \omega_2)} \tilde{\mathbf{E}}_1 \tilde{\mathbf{E}}_2^2 + e^{-3 i t \omega_2} \tilde{\mathbf{E}}_2^3 + 3 e^{-i t \omega_1} \tilde{\mathbf{E}}_1^2 (\tilde{\mathbf{E}}_1)^* +$$

$$6 e^{-i t \omega_2} \tilde{\mathbf{E}}_1 \tilde{\mathbf{E}}_2 (\tilde{\mathbf{E}}_1)^* + 3 e^{i t (\omega_1 - 2 \omega_2)} \tilde{\mathbf{E}}_2^2 (\tilde{\mathbf{E}}_1)^* + 3 e^{i t \omega_1} \tilde{\mathbf{E}}_1 ((\tilde{\mathbf{E}}_1)^*)^2 + 3 e^{i t (2 \omega_1 - \omega_2)} \tilde{\mathbf{E}}_2 ((\tilde{\mathbf{E}}_1)^*)^2 +$$

$$e^{3 i t \omega_1} ((\tilde{\mathbf{E}}_1)^*)^3 + 3 e^{i t (-2 \omega_1 + \omega_2)} \tilde{\mathbf{E}}_1^2 (\tilde{\mathbf{E}}_2)^* + 6 e^{-i t \omega_1} \tilde{\mathbf{E}}_1 \tilde{\mathbf{E}}_2 (\tilde{\mathbf{E}}_2)^* + 3 e^{-i t \omega_2} \tilde{\mathbf{E}}_2^2 (\tilde{\mathbf{E}}_2)^* +$$

$$6 e^{i t \omega_2} \tilde{\mathbf{E}}_1 (\tilde{\mathbf{E}}_1)^* (\tilde{\mathbf{E}}_2)^* + 6 e^{i t \omega_1} \tilde{\mathbf{E}}_2 (\tilde{\mathbf{E}}_1)^* (\tilde{\mathbf{E}}_2)^* + 3 e^{i t (2 \omega_1 + \omega_2)} ((\tilde{\mathbf{E}}_1)^*)^2 (\tilde{\mathbf{E}}_2)^* +$$

$$3 e^{i t (-\omega_1 + 2 \omega_2)} \tilde{\mathbf{E}}_1 ((\tilde{\mathbf{E}}_2)^*)^2 + 3 e^{i t \omega_2} \tilde{\mathbf{E}}_2 ((\tilde{\mathbf{E}}_2)^*)^2 + 3 e^{i t (\omega_1 + 2 \omega_2)} (\tilde{\mathbf{E}}_1)^* ((\tilde{\mathbf{E}}_2)^*)^2 + e^{3 i t \omega_2} ((\tilde{\mathbf{E}}_2)^*)^3)$$

The frequencies are

```

PNL ==  $\frac{1}{8} \epsilon_0 \chi_3 \left( e^{-3 i t \omega_1} \tilde{E}_1^3 + 3 e^{i t (-2 \omega_1 - \omega_2)} \tilde{E}_1^2 \tilde{E}_2 + 3 e^{i t (-\omega_1 - 2 \omega_2)} \tilde{E}_1 \tilde{E}_2^2 + e^{-3 i t \omega_2} \tilde{E}_2^3 + 3 e^{-i t \omega_1} \tilde{E}_1^2 (\tilde{E}_1)^* + \right.$ 
 $6 e^{-i t \omega_2} \tilde{E}_1 \tilde{E}_2 (\tilde{E}_1)^* + 3 e^{i t (\omega_1 - 2 \omega_2)} \tilde{E}_2^2 (\tilde{E}_1)^* + 3 e^{i t \omega_1} \tilde{E}_1 ((\tilde{E}_1)^*)^2 + 3 e^{i t (2 \omega_1 - \omega_2)} \tilde{E}_2 ((\tilde{E}_1)^*)^2 +$ 
 $e^{3 i t \omega_1} ((\tilde{E}_1)^*)^3 + 3 e^{i t (-2 \omega_1 + \omega_2)} \tilde{E}_1^2 (\tilde{E}_2)^* + 6 e^{-i t \omega_1} \tilde{E}_1 \tilde{E}_2 (\tilde{E}_2)^* + 3 e^{-i t \omega_2} \tilde{E}_2^2 (\tilde{E}_2)^* +$ 
 $6 e^{i t \omega_2} \tilde{E}_1 (\tilde{E}_1)^* (\tilde{E}_2)^* + 6 e^{i t \omega_1} \tilde{E}_2 (\tilde{E}_1)^* (\tilde{E}_2)^* + 3 e^{i t (2 \omega_1 + \omega_2)} ((\tilde{E}_1)^*)^2 (\tilde{E}_2)^* +$ 
 $3 e^{i t (-\omega_1 + 2 \omega_2)} \tilde{E}_1 ((\tilde{E}_2)^*)^2 + 3 e^{i t \omega_2} \tilde{E}_2 ((\tilde{E}_2)^*)^2 + 3 e^{i t (\omega_1 + 2 \omega_2)} (\tilde{E}_1)^* ((\tilde{E}_2)^*)^2 + e^{3 i t \omega_2} ((\tilde{E}_2)^*)^3 \Big)$ 
MPMAF [% , frequencies == Cases [# , ea - , {0 , ∞}] & , At[2] , Take → Last ,
Part , {At[2] , {2}} , Level → 1 ,
MPDiv , {At[2] , i t} ,
Cases , {At[2] , ωi | 2 ωi - ωj} , Apply → Union]
    
```

```

PNL ==  $\frac{1}{8} \epsilon_0 \chi_3 \left( e^{-3 i t \omega_1} \tilde{E}_1^3 + 3 e^{i t (-2 \omega_1 - \omega_2)} \tilde{E}_1^2 \tilde{E}_2 + 3 e^{i t (-\omega_1 - 2 \omega_2)} \tilde{E}_1 \tilde{E}_2^2 + e^{-3 i t \omega_2} \tilde{E}_2^3 + 3 e^{-i t \omega_1} \tilde{E}_1^2 (\tilde{E}_1)^* + \right.$ 
 $6 e^{-i t \omega_2} \tilde{E}_1 \tilde{E}_2 (\tilde{E}_1)^* + 3 e^{i t (\omega_1 - 2 \omega_2)} \tilde{E}_2^2 (\tilde{E}_1)^* + 3 e^{i t \omega_1} \tilde{E}_1 ((\tilde{E}_1)^*)^2 + 3 e^{i t (2 \omega_1 - \omega_2)} \tilde{E}_2 ((\tilde{E}_1)^*)^2 +$ 
 $e^{3 i t \omega_1} ((\tilde{E}_1)^*)^3 + 3 e^{i t (-2 \omega_1 + \omega_2)} \tilde{E}_1^2 (\tilde{E}_2)^* + 6 e^{-i t \omega_1} \tilde{E}_1 \tilde{E}_2 (\tilde{E}_2)^* + 3 e^{-i t \omega_2} \tilde{E}_2^2 (\tilde{E}_2)^* +$ 
 $6 e^{i t \omega_2} \tilde{E}_1 (\tilde{E}_1)^* (\tilde{E}_2)^* + 6 e^{i t \omega_1} \tilde{E}_2 (\tilde{E}_1)^* (\tilde{E}_2)^* + 3 e^{i t (2 \omega_1 + \omega_2)} ((\tilde{E}_1)^*)^2 (\tilde{E}_2)^* +$ 
 $3 e^{i t (-\omega_1 + 2 \omega_2)} \tilde{E}_1 ((\tilde{E}_2)^*)^2 + 3 e^{i t \omega_2} \tilde{E}_2 ((\tilde{E}_2)^*)^2 + 3 e^{i t (\omega_1 + 2 \omega_2)} (\tilde{E}_1)^* ((\tilde{E}_2)^*)^2 + e^{3 i t \omega_2} ((\tilde{E}_2)^*)^3 \Big)$ 
    
```

```

frequencies == {-3 ω1 , -2 ω1 - ω2 , -ω1 - 2 ω2 , -3 ω2 , -ω1 , -ω2 , ω1 - 2 ω2 , ω1 ,
2 ω1 - ω2 , 3 ω1 , -2 ω1 + ω2 , -ω1 , -ω2 , ω2 , ω1 , 2 ω1 + ω2 , -ω1 + 2 ω2 , ω2 , ω1 + 2 ω2 , 3 ω2}
frequencies == {ω1 , 2 ω1 - ω2 , ω2 , -ω1 + 2 ω2}
    
```

Four frequencies are present in the output wave and they are in the order

```
frequencies == {2 ω1 - ω2 , ω1 , ω2 , -ω1 + 2 ω2}
```

if $\omega_1 < \omega_2$.

Functions

- **Mathematical Functions** (*Mathematica Guide*)

Programming

- **Procedural Programming** (*Mathematica Guide*)
- **Defining Functions** (*Mathematica Tutorial*)
- Functions can be called recursively.

```
f[n_] := n f[n - 1] ; f[0] = 1 ;
```

```
f[100]
```

```
93 326 215 443 944 152 681 699 238 856 266 700 490 715 968 264 381 621 468 592 963 895 217 599 993 229 \
915 608 941 463 976 156 518 286 253 697 920 827 223 758 251 185 210 916 864 000 000 000 000 000 000 \
000 000
```

```
100 !
```

```
93 326 215 443 944 152 681 699 238 856 266 700 490 715 968 264 381 621 468 592 963 895 217 599 993 229 \
915 608 941 463 976 156 518 286 253 697 920 827 223 758 251 185 210 916 864 000 000 000 000 000 000 \
000 000
```

```
Clear[f]
```

- **Functional Programming (*Mathematica* Guide)**
- **Pure Functions (*Mathematica* Tutorial)**
- **Functional Operations (*Mathematica* Overview)**
- **Example: data manipulation**

– Generate the data

```
data = RandomReal[{-10, 10}, 100]
```

```
{9.2069, 4.38196, 7.36707, 2.44153, -2.71293, -7.84716, -2.51371, -7.20865, -0.35902,
0.547298, -5.73894, 6.72848, 0.891682, 6.47749, 2.32973, -1.13296, -9.28741, 2.6097,
-3.3001, 1.31403, 3.28091, -6.56867, -4.45742, -3.50691, -5.22019, -7.31909,
8.72281, 2.20909, -1.75738, 8.50959, 4.91354, 7.45721, 5.48025, -1.42342, 9.46615,
4.72104, 7.33425, -1.08151, 5.55214, 2.43006, 8.78305, -8.43983, -1.63389,
-5.64446, -6.33726, 6.14862, -5.05503, 7.83732, 9.89825, -6.70792, -1.25488,
5.78948, -6.64355, -4.31986, 5.54391, 5.09748, 4.97521, -7.33067, -5.96476,
0.273494, 4.95501, -9.22198, -4.24909, -6.01423, 1.07997, -0.97207, -0.425487,
1.10524, 4.61603, -1.08979, -4.19288, -4.14596, 0.206045, -3.44104, -5.51746,
-3.39021, 4.92202, -8.64063, -2.70173, 2.66111, 7.56427, 3.89614, 4.80096,
-7.25148, -9.66792, 2.19267, -8.06609, 2.25114, 5.52372, 9.20761, -7.88423,
4.23404, -6.21864, 6.96702, 5.57343, 7.28515, 9.36244, -4.81503, 6.72125, -0.399189}
```

– Number of data

```
Length[data]
```

```
100
```

– Addition of all data

```
Plus @@ data
```

```
34.7723
```

– Select positive numbers

```
Select[data, Negative]
```

```
{-2.71293, -7.84716, -2.51371, -7.20865, -0.35902, -5.73894, -1.13296, -9.28741,
-3.3001, -6.56867, -4.45742, -3.50691, -5.22019, -7.31909, -1.75738, -1.42342,
-1.08151, -8.43983, -1.63389, -5.64446, -6.33726, -5.05503, -6.70792, -1.25488,
-6.64355, -4.31986, -7.33067, -5.96476, -9.22198, -4.24909, -6.01423, -0.97207,
-0.425487, -1.08979, -4.19288, -4.14596, -3.44104, -5.51746, -3.39021, -8.64063,
-2.70173, -7.25148, -9.66792, -8.06609, -7.88423, -6.21864, -4.81503, -0.399189}
```

```
Cases[data, _?Negative]
```

```
{-2.71293, -7.84716, -2.51371, -7.20865, -0.35902, -5.73894, -1.13296, -9.28741,
-3.3001, -6.56867, -4.45742, -3.50691, -5.22019, -7.31909, -1.75738, -1.42342,
-1.08151, -8.43983, -1.63389, -5.64446, -6.33726, -5.05503, -6.70792, -1.25488,
-6.64355, -4.31986, -7.33067, -5.96476, -9.22198, -4.24909, -6.01423, -0.97207,
-0.425487, -1.08979, -4.19288, -4.14596, -3.44104, -5.51746, -3.39021, -8.64063,
-2.70173, -7.25148, -9.66792, -8.06609, -7.88423, -6.21864, -4.81503, -0.399189}
```

– Select data larger than 5

```
Select[data, # > 5 &]
```

```
{7.97756, 7.06071, 6.25687, 7.77989, 8.95827, 9.383, 6.92007, 6.09351,
9.35384, 8.79465, 6.81701, 9.68147, 5.23082, 6.14421, 8.4387, 6.12878,
7.46329, 6.51098, 9.32175, 8.12827, 9.10668, 9.73478, 8.44398, 6.23945}
```

```
Cases[data, _? (# > 5 &)]
```

```
{7.97756, 7.06071, 6.25687, 7.77989, 8.95827, 9.383, 6.92007, 6.09351,
9.35384, 8.79465, 6.81701, 9.68147, 5.23082, 6.14421, 8.4387, 6.12878,
7.46329, 6.51098, 9.32175, 8.12827, 9.10668, 9.73478, 8.44398, 6.23945}
```

– Group two numbers and add the numbers in each group.

```
Partition[#, 2] &@data  
Plus @@@ %
```

```
{{9.2069, 4.38196}, {7.36707, 2.44153}, {-2.71293, -7.84716}, {-2.51371, -7.20865},  
{-0.35902, 0.547298}, {-5.73894, 6.72848}, {0.891682, 6.47749}, {2.32973, -1.13296},  
{-9.28741, 2.6097}, {-3.3001, 1.31403}, {3.28091, -6.56867}, {-4.45742, -3.50691},  
{-5.22019, -7.31909}, {8.72281, 2.20909}, {-1.75738, 8.50959}, {4.91354, 7.45721},  
{5.48025, -1.42342}, {9.46615, 4.72104}, {7.33425, -1.08151}, {5.55214, 2.43006},  
{8.78305, -8.43983}, {-1.63389, -5.64446}, {-6.33726, 6.14862},  
{-5.05503, 7.83732}, {9.89825, -6.70792}, {-1.25488, 5.78948}, {-6.64355, -4.31986},  
{5.54391, 5.09748}, {4.97521, -7.33067}, {-5.96476, 0.273494}, {4.95501, -9.22198},  
{-4.24909, -6.01423}, {1.07997, -0.97207}, {-0.425487, 1.10524}, {4.61603, -1.08979},  
{-4.19288, -4.14596}, {0.206045, -3.44104}, {-5.51746, -3.39021},  
{4.92202, -8.64063}, {-2.70173, 2.66111}, {7.56427, 3.89614}, {4.80096, -7.25148},  
{-9.66792, 2.19267}, {-8.06609, 2.25114}, {5.52372, 9.20761}, {-7.88423, 4.23404},  
{-6.21864, 6.96702}, {5.57343, 7.28515}, {9.36244, -4.81503}, {6.72125, -0.399189}}  
  
{13.5889, 9.8086, -10.5601, -9.72236, 0.188278, 0.989546, 7.36917, 1.19678, -6.67771,  
-1.98607, -3.28776, -7.96432, -12.5393, 10.9319, 6.75221, 12.3708, 4.05682,  
14.1872, 6.25274, 7.9822, 0.343213, -7.27836, -0.188635, 2.78229, 3.19033, 4.53461,  
-10.9634, 10.6414, -2.35546, -5.69127, -4.26698, -10.2633, 0.107901, 0.679749,  
3.52624, -8.33884, -3.235, -8.90766, -3.7186, -0.040626, 11.4604, -2.45052,  
-7.47525, -5.81495, 14.7313, -3.65019, 0.748378, 12.8586, 4.54741, 6.32206}
```

Packages

Packages

- **Mathematica Packages** (*Mathematica Tutorial*)
- **Package Development** (*Mathematica Guide*)
- **A sample package**

Sample.m

```
<< Sample`
```

```
Context[AddTwo]
```

```
Sample`
```

```
AddTwo[a, b]
```

```
AddTwo[a, b]
```

```
Remove[Sample`AddTwo]
```

```
Remove[Global`AddTwo]
```

Communication with External Programs

- **Introduction to *MathLink*** (*Mathematica Tutorial*)
- ***MathLink* C API Developer Guide** (Windows)
- ***MathLink* API** (*Mathematica Guide*)
- **Example (addtwo.exe)**
- **addtwo.c**

```
#include "mathlink.h"  
extern int addtwo( int i, int j);  
int addtwo( int i, int j)  
{  
    return i+j;  
}
```


- **addtwo.tm**

```
int addtwo P(( int, int));
:Begin:
:Function:    addtwo
:Pattern:    AddTwo[i_Integer, j_Integer]
:Arguments:   { i, j }
:ArgumentTypes: { Integer, Integer }
:ReturnType: Integer
:End:
:Evaluate: AddTwo::usage = "AddTwo[x, y] gives the sum of two machine integers x and y."
```

- **Compile and link**

```
SET CL=/nologo /c /DWIN32 /D_WINDOWS /W3 /O2 /DNDEBUG /IInclude
SET LINK=/NOLOGO /SUBSYSTEM:windows /INCREMENTAL:no kernel32.lib
user32.lib gdi32.lib /LIBPATH:\Lib
MPREP addtwo.tm -o addtwotm.c
CL addtwo.c addtwotm.c
LINK addtwo.obj addtwotm.obj ml32i2m.lib /OUT:addtwo.exe
```

- **Install and run**

Install

```
mlelink = Install["I:/Mathematica/MathLink/MathLinkExamples/addtwo/addtwo.exe"];
```

The two arguments must be integers.

```
AddTwo[1, 2]
```

3

```
AddTwo[1.0, 2.0]
```

AddTwo[1., 2.]

Uninstall.

```
Uninstall[mlelink]
```

"I:\Mathematica\MathLink\MathLinkExamples\addtwo\addtwo.exe"

- **Example (Modeling of Optical Fiber Modes)**

- **Initialization**

- Open the *MathLink* connection.

– Windows

```
mlelink = Install["mle.exe"];
```

– Unix

```
mlelink = Install[LinkConnect["aaa"]];
```

– Uninstall

```
Uninstall[mlelink]
```

mle.exe

- Set the default directory.

```
SetDirectory["D:/Temp"]
```

D:\Temp

```
Directory[]
```

D:\Temp

- Turn off Sellmeier formula by default.

```
DspnSetSellmeier[False];
```

- **Refractive Index Profiles**

- Step index

The data format for the step index profile is

$$\{\text{Step}, n_{\text{core}}, \{a_{\text{core-clad}}, n_{\text{clad}}\}\}$$

or

$$\{\text{Step}, \Delta_{\text{core}}, \{a_{\text{core-clad}}, \Delta_{\text{clad}}\}\}.$$

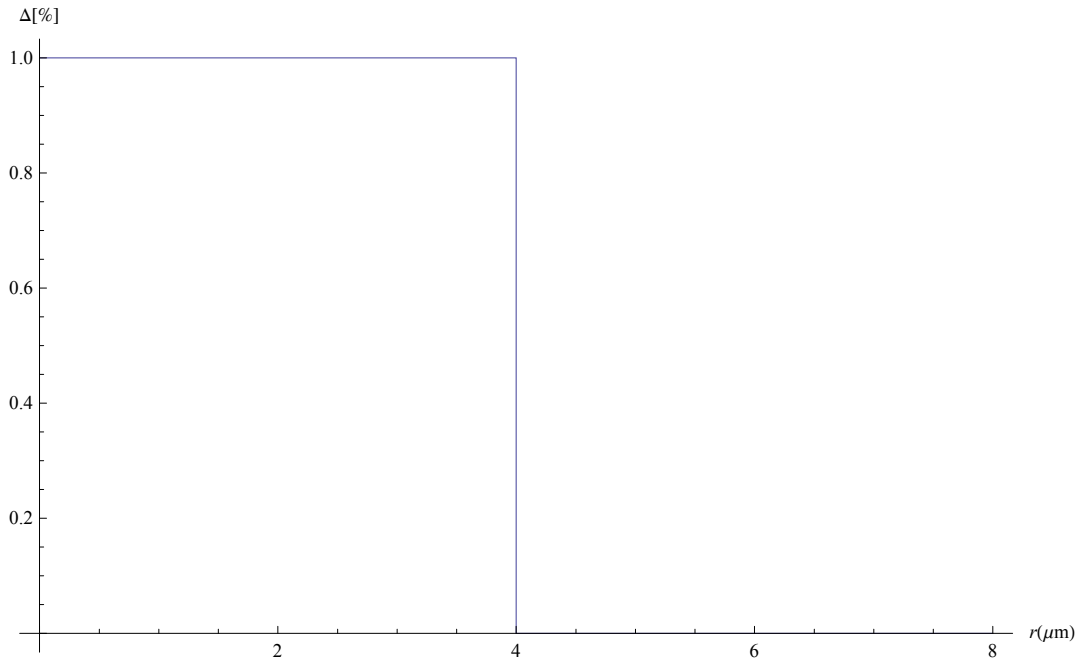
Δ is given in percent (%).

```

profile = {Step, 1, {4, 0}}
DspnPlotIndex[1.55, profile, Scale → Delta,
  AxesLabel → {r[μm], "Δ[%]"}, ImageSize → 500]

```

```
{Step, 1, {4, 0}}
```



- α -index

The data format for the α index profile is

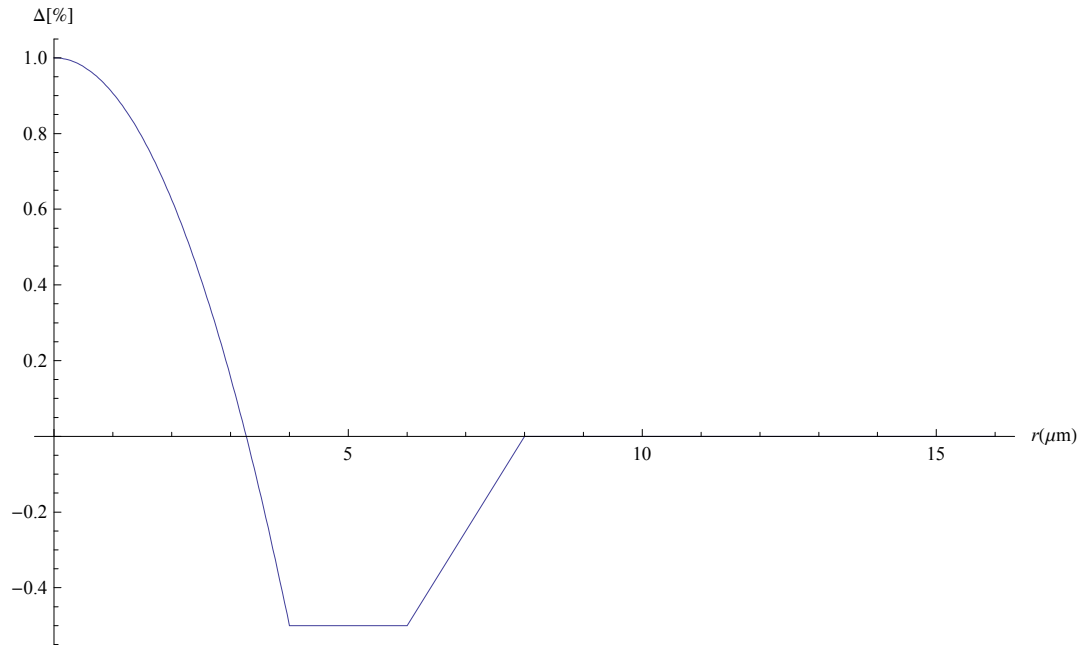
$\{\text{Alpha}, \alpha, \{\{0, n_{\text{core}}\}, \{a_{\text{core}}, n_1\}, \{r_2, n_2\}, \dots, \{r_N, n_N\}, \{a_{\text{core-clad}}, n_{\text{clad}}\}\}$

or

$\{\text{Alpha}, \alpha, \{\{0, \Delta_{\text{core}}\}, \{a_{\text{core}}, \Delta_1\}, \{r_2, \Delta_2\}, \dots, \{r_N, \Delta_N\}, \{a_{\text{core-clad}}, \Delta_{\text{clad}}\}\}\}$.

```
profile = {Alpha, 2, {{0, 1}, {4, -0.5}, {6, -0.5}, {8, 0}}}  
DspnPlotIndex[1.55, profile, Scale → Delta,  
  AxesLabel → {r[μm], "Δ[%]"}, ImageSize → 500]
```

```
{Alpha, 2, {{0, 1}, {4, -0.5}, {6, -0.5}, {8, 0}}}
```



- General index

The data format for the general index profile is

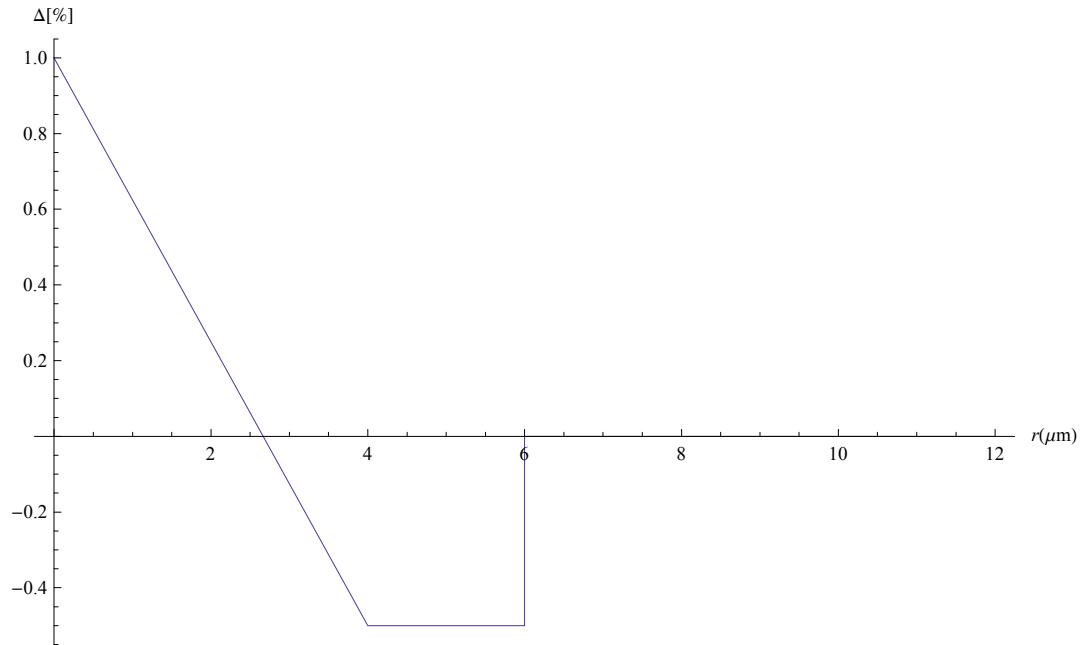
$\{\text{General}, \{0, n_{\text{core}}\}, \{r_1, n_1\}, \{r_2, n_2\}, \dots, \{r_N, n_N\}, \{a_{\text{core-clad}}, n_{\text{clad}}\}\}$

or

$\{\text{General}, \{0, \Delta_{\text{core}}\}, \{r_1, \Delta_1\}, \{r_2, \Delta_2\}, \dots, \{r_N, \Delta_N\}, \{a_{\text{core-clad}}, \Delta_{\text{clad}}\}\}$.

```
profile = {General, {{0, 1}, {4, -0.5}, {6, -0.5}, {6, 0}}}
DspnPlotIndex[1.55, profile, Scale → Delta,
  AxesLabel → {r[μm], "Δ[%]"}, ImageSize → 500]
```

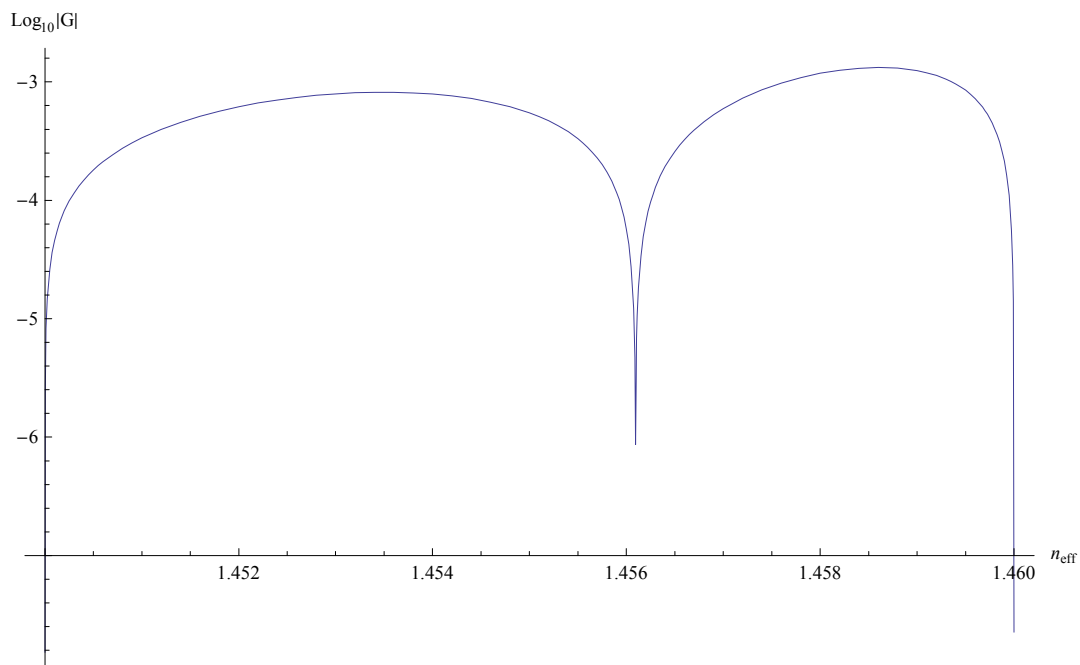
```
{General, {{0, 1}, {4, -0.5}, {6, -0.5}, {6, 0}}}
```



■ Characteristic Equation

- Plot the characteristic equation.

```
profile = {Step, 1.46, {4, 1.45}};
DspnPlotCharEquation[1, 1.55, profile,
  AxesLabel → {"neff", "Log10|G|"}, ImageSize → 500]
```



■ Effective Index, Group Index, and Dispersion

Effective Index, Group Index, and Dispersion

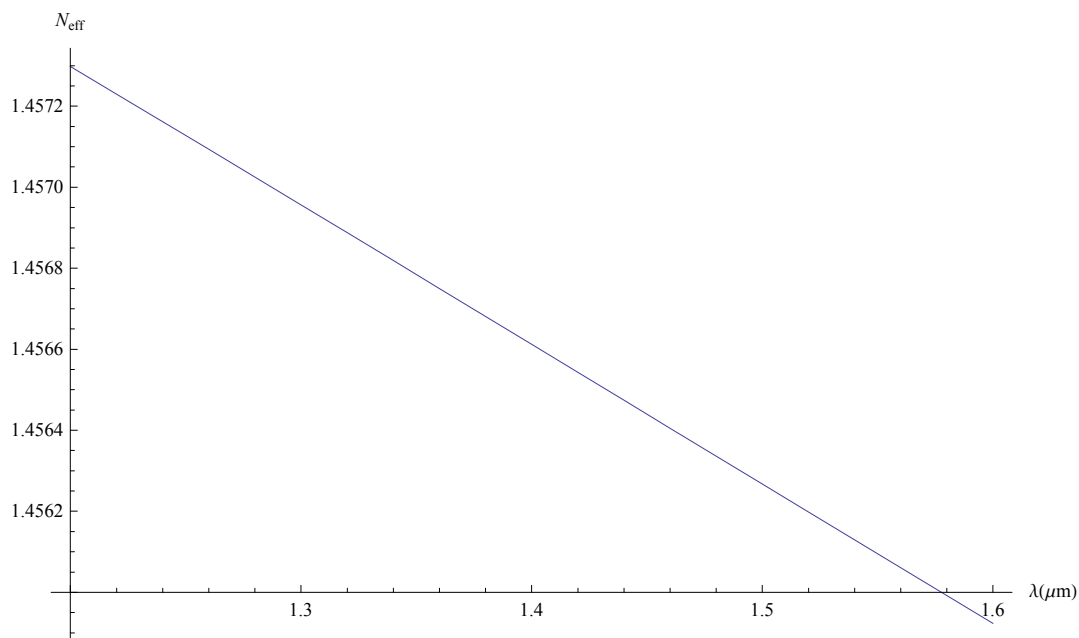
- Calculate the effective indexes, group indexes and dispersion of the guided modes.

```
profile = {Step, 1.46, {4, 1.45}};
sols = DspnNeffNgroupDspn[1, {1.2, 1.6, 0.02}, profile, NumModes -> 1]
```

```
{Mode -> {HE1,1}, Lambda -> {1.2, 1.22, 1.24, 1.26, 1.28, 1.3, 1.32, 1.34,
  1.36, 1.38, 1.4, 1.42, 1.44, 1.46, 1.48, 1.5, 1.52, 1.54, 1.56, 1.58, 1.6},
Neff -> {{1.4573, 1.45723, 1.45716, 1.45709, 1.45702, 1.45696, 1.45689,
  1.45682, 1.45675, 1.45668, 1.45661, 1.45654, 1.45647, 1.45641,
  1.45634, 1.45627, 1.4562, 1.45613, 1.45606, 1.45599, 1.45592}},
Ngroup -> {{1.46137, 1.46138, 1.46139, 1.4614, 1.46141, 1.46142, 1.46143,
  1.46143, 1.46144, 1.46144, 1.46144, 1.46144, 1.46144, 1.46144,
  1.46144, 1.46143, 1.46143, 1.46142, 1.46142, 1.46141, 1.4614}},
Dspn -> {{2.10049, 1.93054, 1.75769, 1.58207, 1.4038, 1.22301, 1.03981, 0.854336,
  0.666699, 0.477018, 0.285407, 0.0919793, -0.103155, -0.299888, -0.498114,
  -0.697731, -0.898639, -1.10074, -1.30395, -1.50817, -1.71333}}}
```

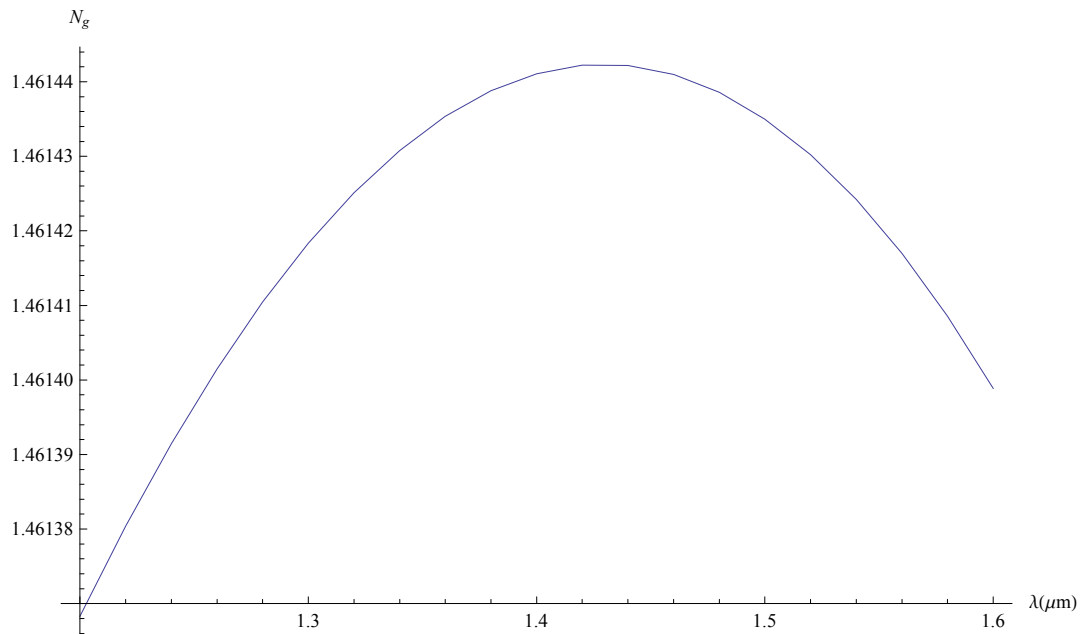
- Plot the effective index N_{eff}

```
ListPlot[Transpose[{Lambda /. sols, (Neff /. sols)[[1]]}],
Joined -> True, AxesLabel -> {λ[μm], Neff}, ImageSize -> 500]
```



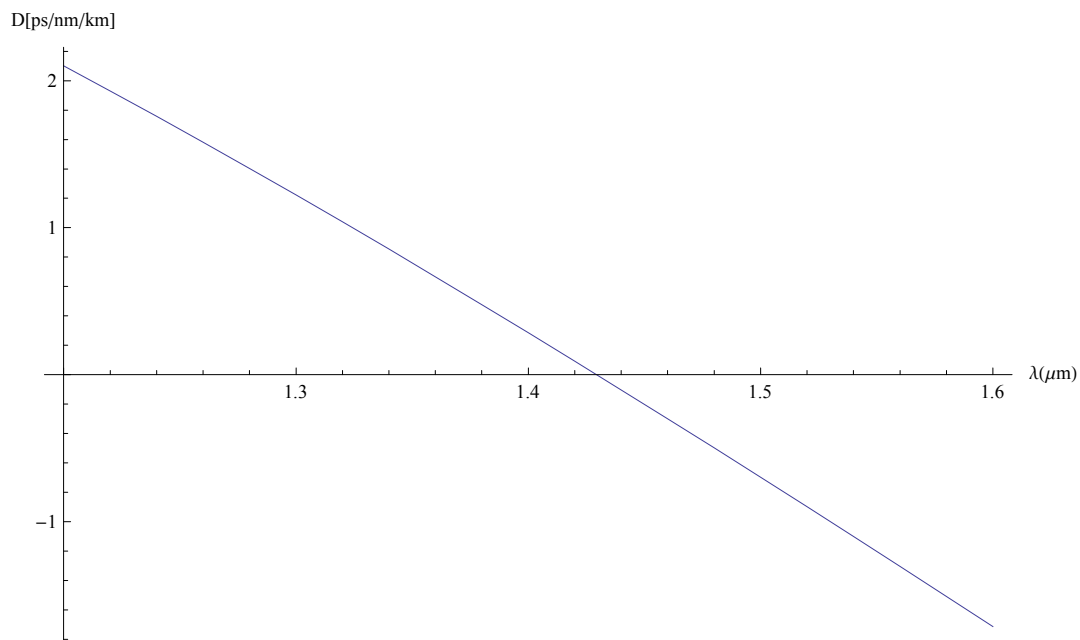
- Plot the group index N_g

```
ListPlot[Transpose[{Lambda /. sols, (Ngroup /. sols)[[1]]}],
  Joined → True, AxesLabel → {λ[μm], Ng}, ImageSize → 500]
```



- Plot the dispersion D

```
ListPlot[Transpose[{Lambda /. sols, (Dspn /. sols)[[1]]}],
  Joined → True, AxesLabel → {λ[μm], "D[ps/nm/km]"}, ImageSize → 500]
```



- Poynting Vector and Field Profile

- Calculate the Poynting vector.

```

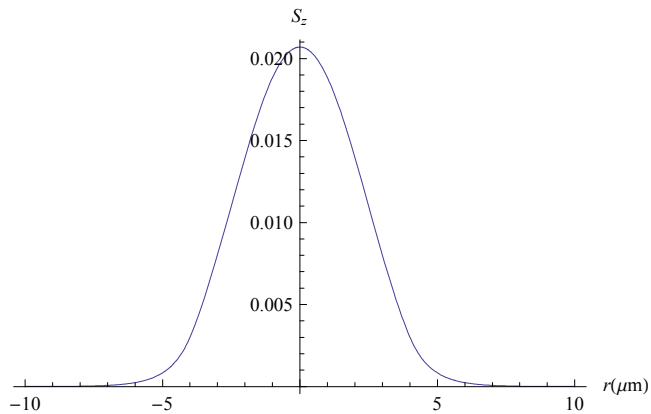
profile = {Step, 1.46, {4, 1.45}};
sols = DspnNeff[1, 1.55, profile]
SetCoordinates[Cartesian[x, y, z]];
ssol = DspnPoyntingVector[1, 1.55, 1, profile, Phase  $\rightarrow \pi/2$ , MaxRadius  $\rightarrow 20$ ];

```

```
{Mode  $\rightarrow$  {HE1,1}, Lambda  $\rightarrow$  1.55, Neff  $\rightarrow$  {1.4561}}
```

- Plot the Poynting vector

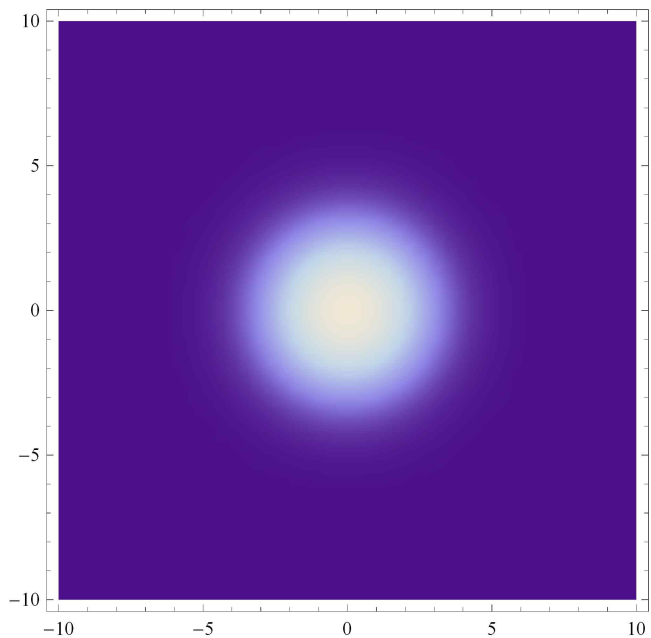
```
Plot[(PoyntingVector[[3]] /. ssol)[x, 0], {x, -10, 10}, AxesLabel  $\rightarrow$  {r[ $\mu$ m], Sz}
```



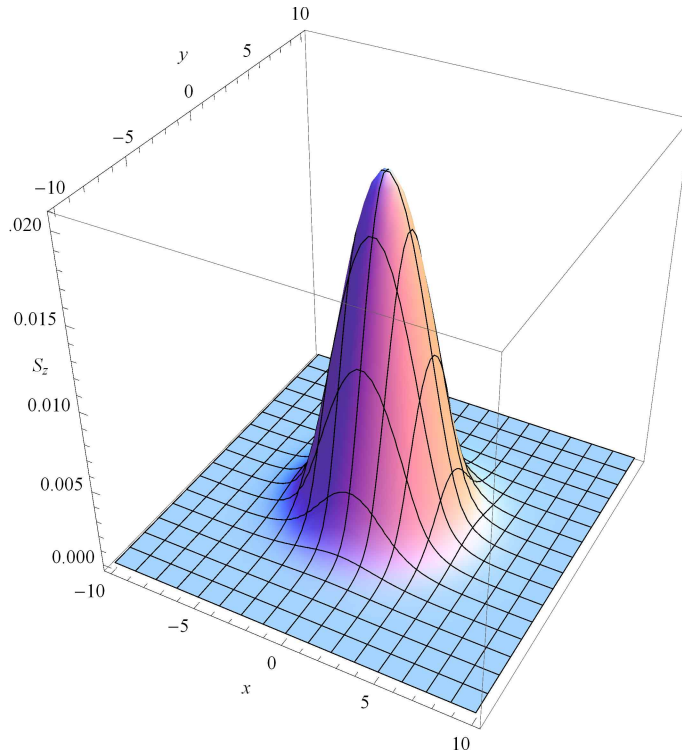
```

DensityPlot[(PoyntingVector[[3]] /. ssol)[x, y],
{x, -10, 10}, {y, -10, 10}, PlotPoints  $\rightarrow$  50, PlotRange  $\rightarrow$  All]

```




```
Plot3D[(PoyntingVector[[3]] /. ssol)[x, y], {x, -10, 10}, {y, -10, 10},
  AxesLabel -> {x, y, Sz}, BoxRatios -> {1, 1, 1}, PlotPoints -> 50, PlotRange -> All]
```



- **Example (Hardware Control via GPIB)**

- **Initialization**

- Open the *MathLink* connection.

```
mlelink = Install["mle.exe"];
```

```
mlelink = Install[LinkConnect["aaa"]];
```

```
Uninstall[mlelink]
```

mle.exe

- Initialization of the GPIB interface for data acquisition and control.

```
GPIBInitialize[{"GPIB0", 0, IsBoard -> True},
  {"tds360", 1, Timeout -> 11}, {"hp3245a", 9, Timeout -> 11}]
```

```
board = "GPIB0", address = 0, eos = 10, timeout = 10
device = "tds360", address = 1, board = "GPIB0", eos = 10, timeout = 11
device = "hp3245a", address = 9, board = "GPIB0", eos = 10, timeout = 11
```

```
GPIBIfClear["GPIB0"]
```

Interface cleared: board "GPIB0".

- Set the default directory.

```
SetDirectory["D:/Temp"]
```

D:\Temp

```
Directory[]
```

D:\Temp

■ Communication Examples

- Identification of the equipment

```
GPIBClear["tds360"];
GPIBWrite["tds360", "*IDN?"];
GPIBRead["tds360"]
```

TEKTRONIX,TDS 360,0,CF:91.1CT FV:v1.09

- Retrieve the data from the equipment and store the data to a file.

```
GPIBWrite["tds360", "CURVe?"];
GPIBReadFile["tds360", "data.txt", Timeout -> 11, Delete -> True]
```

Read to file: device "tds360" to file "D:\Temp\data.txt".

- Switch the data source to Channel 1.

```
GPIBWrite["tds360", "DATA:SOURCE CH1"];
```

- Verify the data source.

```
GPIBWrite["tds360", "DATA:SOURCE?"];
GPIBRead["tds360"]
```

:DAT:SOU CH1

■ Square Pulses and the Fourier Spectrum

- Set the amplitude and frequency of the signal source.

```
GPIBWrite["hp3245a", "RST"];
GPIBWrite["hp3245a", "APPLY SQV 1.0"];
GPIBWrite["hp3245a", "FREQ 1E3"];
```

- Read the data from the oscilloscope and store the data in the variable "data".

```

GPiBWrite["tds360", "CURVe?"];
data = GPiBRead["tds360", TimeOut -> 11];

```

- Parse the data and put the t and y data in the variable "pdata". The format of "pdata" is $\{\{t_1, y_1\}, \{t_2, y_2\}, \dots\}$. The time t_i is in the unit of second and the data y_i is in the unit of volt.

```

GPiBClear["tds360"];
GPiBWrite["tds360", "WFMPre:CH1:XINcr?"];
xinc = ToExpression[
  StringReplace[Part[StringSplit[GPiBRead["tds360"], " "], 2], "E" -> "*^"];
GPiBWrite["tds360", "WFMPre:CH1:YMuIt?"];
ymu = ToExpression[StringReplace[
  Part[StringSplit[GPiBRead["tds360", TimeOut -> 12], " "], 2], "E" -> "*^"];
adata = StringDrop[data, 6];
pdata = ToExpression /@ StringSplit[adata, ","];
pdata = Table[{xinc * i, ymu * pdata[[i]]}, {i, Length[pdata]};
Length[pdata]

```

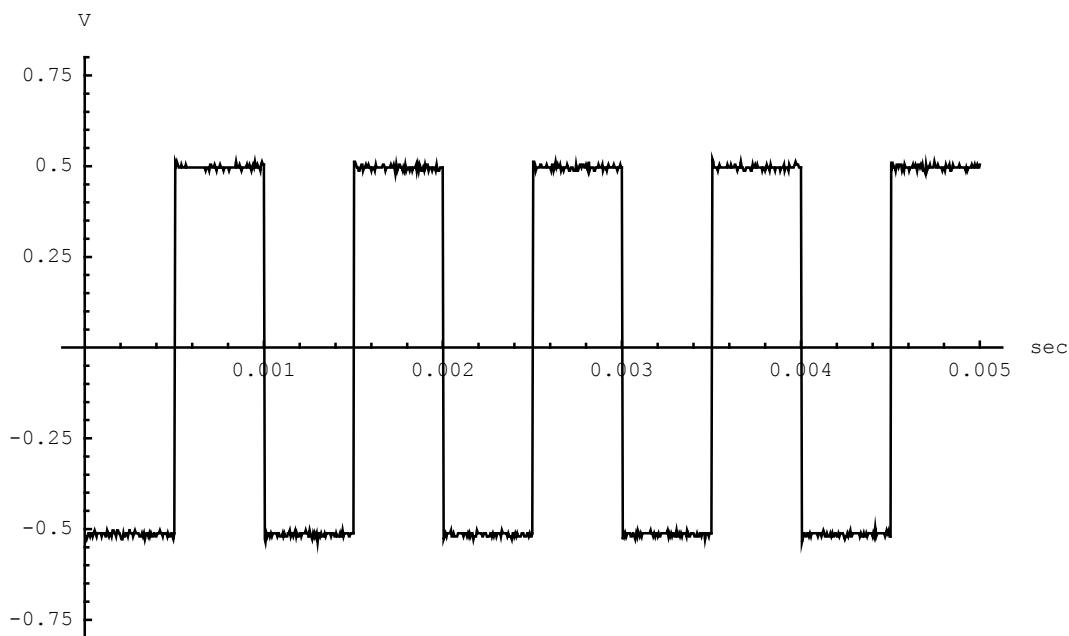
1000

- Plot the data.

```

ListPlot[pdata, Joined -> True, ImageSize -> 500,
  PlotRange -> {-0.8, 0.8}, AxesLabel -> {"sec", "V"}]

```



- Graphics -

- Fourier transform. First separate the time and signal data. Put the time data in the variable "t" and the signal data in the variable "y".

```

{t, y} = Transpose[pdata];

```

The frequency data

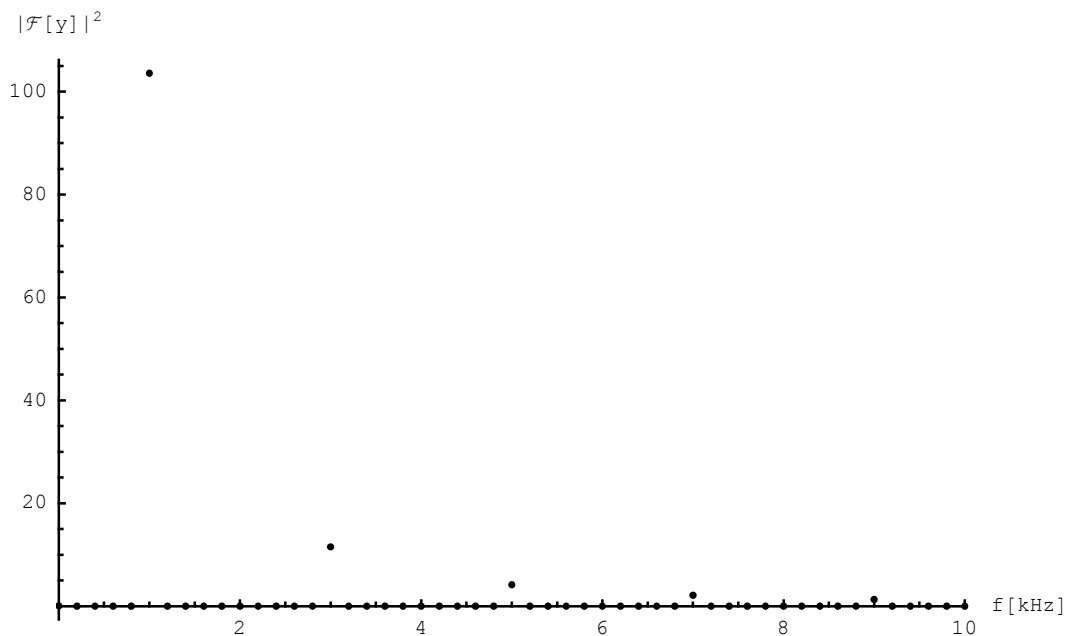
```
f =  $\frac{1}{\text{Length}[t] (t[[2]] - t[[1]])}$  (Range[Length[t] - 1];
```

The Fourier transform of the signal data

```
fy = Fourier[y];
```

Plot the spectrum data.

```
ListPlot[Transpose[{f * 0.001, (Abs /@ fy)^2}, PlotRange -> {{0, 10}, All},  
ImageSize -> 500, AxesLabel -> {"f [kHz]", "|F[y]|^2"}]
```



- Graphics -

- Clear the data.

```
f = .; t = .;
```

■ Sinusoidal Waves and Curve Fitting

- Set the amplitude and frequency of the signal source.

```
GPIBWrite["hp3245a", "RST"];  
GPIBWrite["hp3245a", "APPLY ACV 1.0"];  
GPIBWrite["hp3245a", "FREQ 1E3];
```

- Read the data from the oscilloscope and store the data in the variable "data".

```
GPIBWrite["tds360", "CURVe?"];  
data = GPIBRead["tds360", TimeOut -> 11];
```

- Parse the data and put the t and y data in the variable "pdata". The format of "pdata" is $\{\{t_1, y_1\}, \{t_2, y_2\}, \dots\}$. The time t_i is in the unit of second and the data y_i is in the unit of volt.

- Parse the data and put the t and y data in the variable "pdata". The format of "pdata" is $\{\{t_1, y_1\}, \{t_2, y_2\}, \dots\}$. The time t_i is in the unit of second and the data y_i is in the unit of volt.

```

GPBIClear["tds360"];
GPBWrite["tds360", "WFMPre:CH1:XINcr?"];
xinc = ToExpression[
  StringReplace[Part[StringSplit[GPBRead["tds360"], " "], 2], "E" -> "*^"];
GPBWrite["tds360", "WFMPre:CH1:YMULT?"];
ymu = ToExpression[StringReplace[
  Part[StringSplit[GPBRead["tds360", Timeout -> 12], " "], 2], "E" -> "*^"];
adata = StringDrop[data, 6];
pdata = ToExpression/@StringSplit[adata, ","];
pdata = Table[{xinc * i, ymu * pdata[[i]]}, {i, Length[pdata]};
Length[pdata]

```

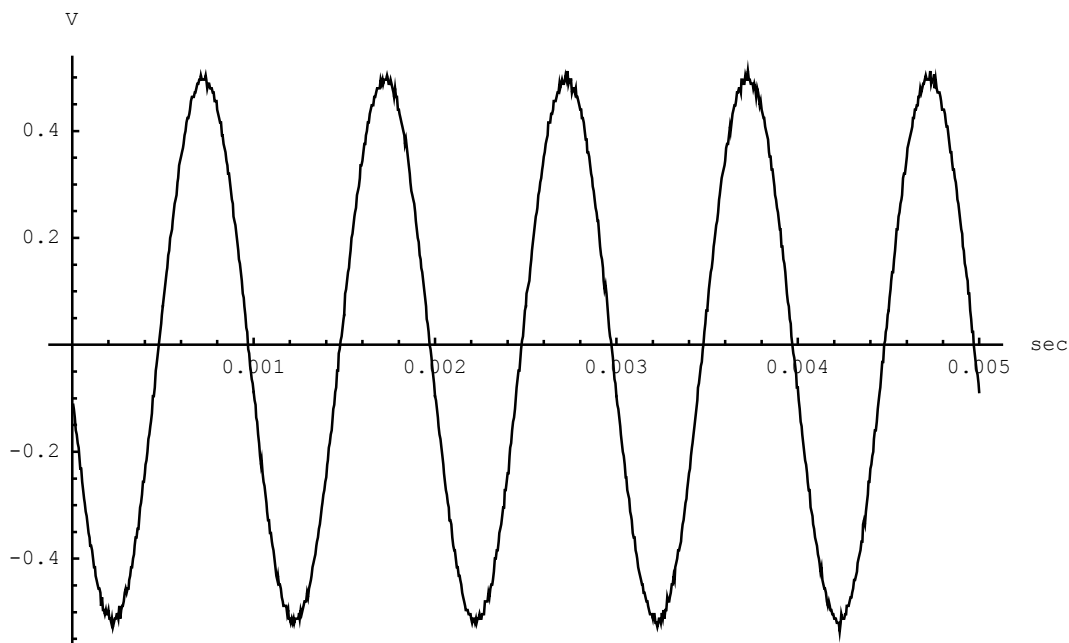
1000

- Plot the data.

```

p11 = ListPlot[pdata, Joined -> True, ImageSize -> 500, AxesLabel -> {"sec", "V"}]

```



- Curve fitting. Fit the data to the sine curve and find the fitting parameters.

```

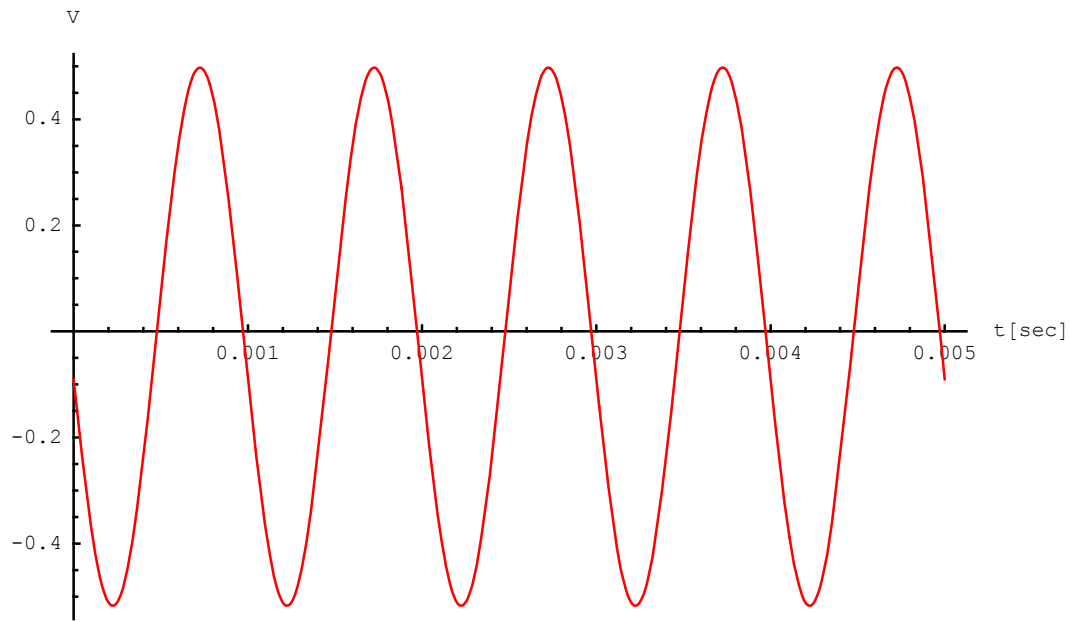
f = 1000;
fitparams = FindFit[pdata, A + B Sin[2 π f t + φ], {A, B, φ}, t]

```

{A -> -0.009912, B -> -0.507288, φ -> 0.159094}

- Plot the sine curve using the fitting parameters.

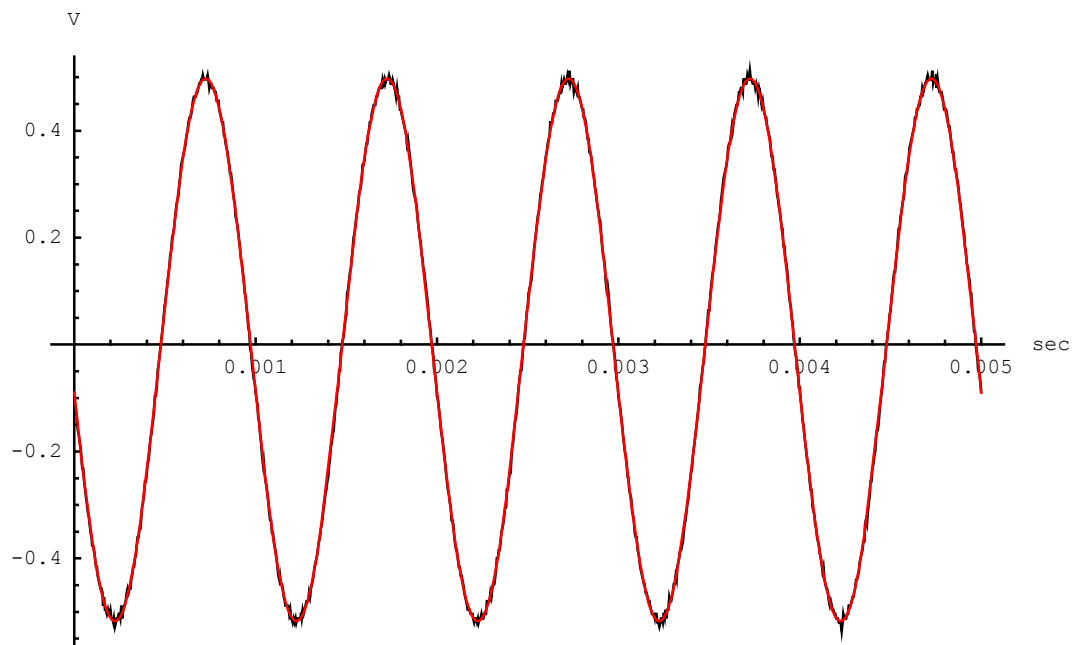
```
p12 = Plot[Evaluate[A + B Sin[2 π f t + φ] /. fitparams], {t, 0, 0.005},
  ImageSize → 500, PlotStyle → {RGBColor[1, 0, 0]}, AxesLabel → {"t[sec]", "V"}]
```



- Graphics -

- Comparison of the original data and the fitting curve.

```
Show[{p11, p12}]
```



- Graphics -

If you want to know more about symbolic computing,

please visit:

<http://ontl.gist.ac.kr>

→ Lectures → Symbolic Computing Methods and
Applications